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~Halaman ini sengaja dikosongkan~

LAMPIRAN A

Program Arduino

```
#include <LiquidCrystal_I2C.h>

#define pin_dht 2
#define pin_servo_window 3
#define pin_servo_feed 9
#define pin_relay_pump 26
#define pin_relay_fan 27
#define pin_relay_conveyor 28
#define pin_relay_mist 29
#define pin_relay_lamp 32
#define pin_sensor_feed A5
#define pin_sensor_water 4
#define pin_ir 6
#define pin_buzzer 53

LiquidCrystal_I2C lcd(0x27, 16, 2);

void setup() {
  Serial.begin(9600);
  Serial1.begin(9600);
  lcd.init();
  lcd.backlight();
  lcd.clear();
  setupServo();
  setupRelay();
  setupLoadcell();
  setupFeed();
  setupWater();
  setupProxy();
  delay(1000);
  setupBuzzer();
  buzzerBeep();
}
```

```

long lastSend = 0;
int display = 0;

boolean isAutoFan = false;
boolean isAutoLamp = false;
boolean isAutoFeed = false;
boolean isAutoWater = false;
boolean isAutoMist = false;

String lastCommandFeed = "";
String lastCommandWater = "";

boolean isFeed = false;
boolean isWater = false;

void loop() {
  float t = dhtGetTemperature();
  float h = dhtGetHumidity();
  bool feed = feedRead();
  bool water = waterRead();
  float weight = loadcellGet();
  if (millis() > lastSend + 3000) {
    String values = "sensor,";
    values += t;
    values += ',';
    values += h;
    values += ',';
    values += feed;
    values += ',';
    values += water;
    values += ',';
    values += weight;
    values += ',';
    Serial.println(values);
    Serial1.println(values);
    if (display < 2) {
      display++;
    } else {
      display = 0;
    }
  }
}

```

```

    }
    lcd.clear();
    lastSend = millis();
}

switch (display) {
  case 0:
    lcd.setCursor(0, 0);
    lcd.print("Temp  : ");
    lcd.print(t);
    lcd.setCursor(0, 1);
    lcd.print("Humidity: ");
    lcd.print(h);
    break;
  case 1:
    lcd.setCursor(0, 0);
    lcd.print("Pakan : ");
    lcd.print(feed);
    lcd.setCursor(0, 1);
    lcd.print("Minum : ");
    lcd.print(water);
    break;
  case 2:
    lcd.setCursor(0, 0);
    lcd.print("Berat kotoran");
    lcd.setCursor(0, 1);
    lcd.print("      ");
    lcd.setCursor(0, 1);
    lcd.print(weight);
    lcd.setCursor(14, 1);
    lcd.print("gr");
    break;
}

if (isAutoFan) {
  if (t > 30) {
    relayFanOn();
  } else {
    relayFanOff();
  }
}

```

```

    }
  }
  if (isAutoLamp) {
    if (t < 25) {
      relayLampOn();
    } else {
      relayLampOff();
    }
  }
  if (isAutoFeed || isFeed) {
    if (feed) {
      servofeedClose();
      isFeed = false;
    } else {
      servofeedOpen();
    }
  }
  if (isAutoWater || isWater) {
    if (water) {
      relayPumpOff();
      isWater = false;
    } else {
      relayPumpOn();
    }
  }
  if (isAutoMist) {
    if (h < 65) {
      relayMistOn();
    } else {
      relayMistOff();
    }
  }

  if (weight > 500) {
    buzzerBeep();
  }
}
//sensor,27.80,79.20,1,0,275.00,

```



```

void serialEvent1() {
  String data = Serial1.readStringUntil('\n');
  Serial.println(data);
  // window
  if (data.indexOf("command_window_on") != -1) {
    servoWindowOpen();
  } else if (data.indexOf("command_window_off") != -1) {
    servoWindowClose();
  }
  // fan
  else if (data.indexOf("command_fan_on") != -1) {
    isAutoFan = false;
    relayFanOn();
  } else if (data.indexOf("command_fan_off") != -1) {
    isAutoFan = false;
    relayFanOff();
  } else if (data.indexOf("command_fan_auto") != -1) {
    isAutoFan = true;
  }
  // lamp
  else if (data.indexOf("command_lamp_on") != -1) {
    isAutoLamp = false;
    relayLampOn();
  } else if (data.indexOf("command_lamp_off") != -1) {
    isAutoLamp = false;
    relayLampOff();
  } else if (data.indexOf("command_lamp_auto") != -1) {
    isAutoLamp = true;
  }
  // feed
  else if (data.indexOf("command_feed_auto") != -1) {
    isAutoFeed = true;
  } else if (data.indexOf("command_feed") != -1) {
    isAutoFeed = false;
    if (lastCommandFeed != "") {
      isFeed = true;
    }
    lastCommandFeed = data;
  }
}

```

```

// water
else if (data.indexOf("command_water_auto") != -1) {
    isAutoWater = true;
} else if (data.indexOf("command_water") != -1) {
    isAutoWater = false;
    if (lastCommandWater != "") {
        isWater = true;
    }
    lastCommandWater = data;
}
// mist
else if (data.indexOf("command_mist_on") != -1) {
    isAutoMist = false;
    relayMistOn();
} else if (data.indexOf("command_mist_off") != -1) {
    isAutoMist = false;
    relayMistOff();
} else if (data.indexOf("command_mist_auto") != -1) {
    isAutoMist = true;
}
// conveyor
else if (data.indexOf("command_conveyor_on") != -1) {
    relayConveyorOn();
} else if (data.indexOf("command_conveyor_off") != -1) {
    relayConveyorOff();
} else if (data.indexOf("command_conveyor_auto") != -1) {
    relayConveyorOn();
    delay(3000);
    while (!read_proximity()) { delay(100); }
    relayConveyorOff();
}
}
}

```

LAMPIRAN B

Dokumentasi Pengujian

a. Tampilan pada LCD



b. Tampilan pada Aplikasi



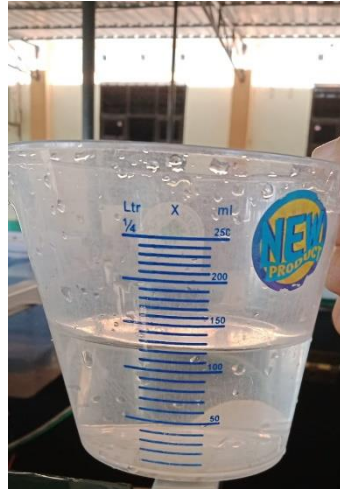
c. Tampilan pada HTC



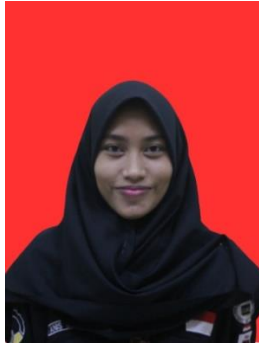
d. Berat pakan



e. Air minum



BIODATA PENULIS



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Telepon/Hp : 0858-4640-5061
Hobi : Travelling
Motto : Jalani, Nikmati, Syukuri

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- SD Negeri Sidanegara 03 Tahun 2008-2014
- SMP Negeri 4 Cilacap Tahun 2014-2017
- SMA Negeri 03 Cilacap Tahun 2017-2020
- Politeknik Negeri Cilacap Tahun 2020-2023

Penulis telah mengikuti sidang Tugas Akhir pada tanggal 18 Agustus 2023 sebagai salah satu persyaratan untuk memperoleh gelar Ahli Madya (A.Md).