







LAMPIRAN A

Dokumentasi Kegiatan

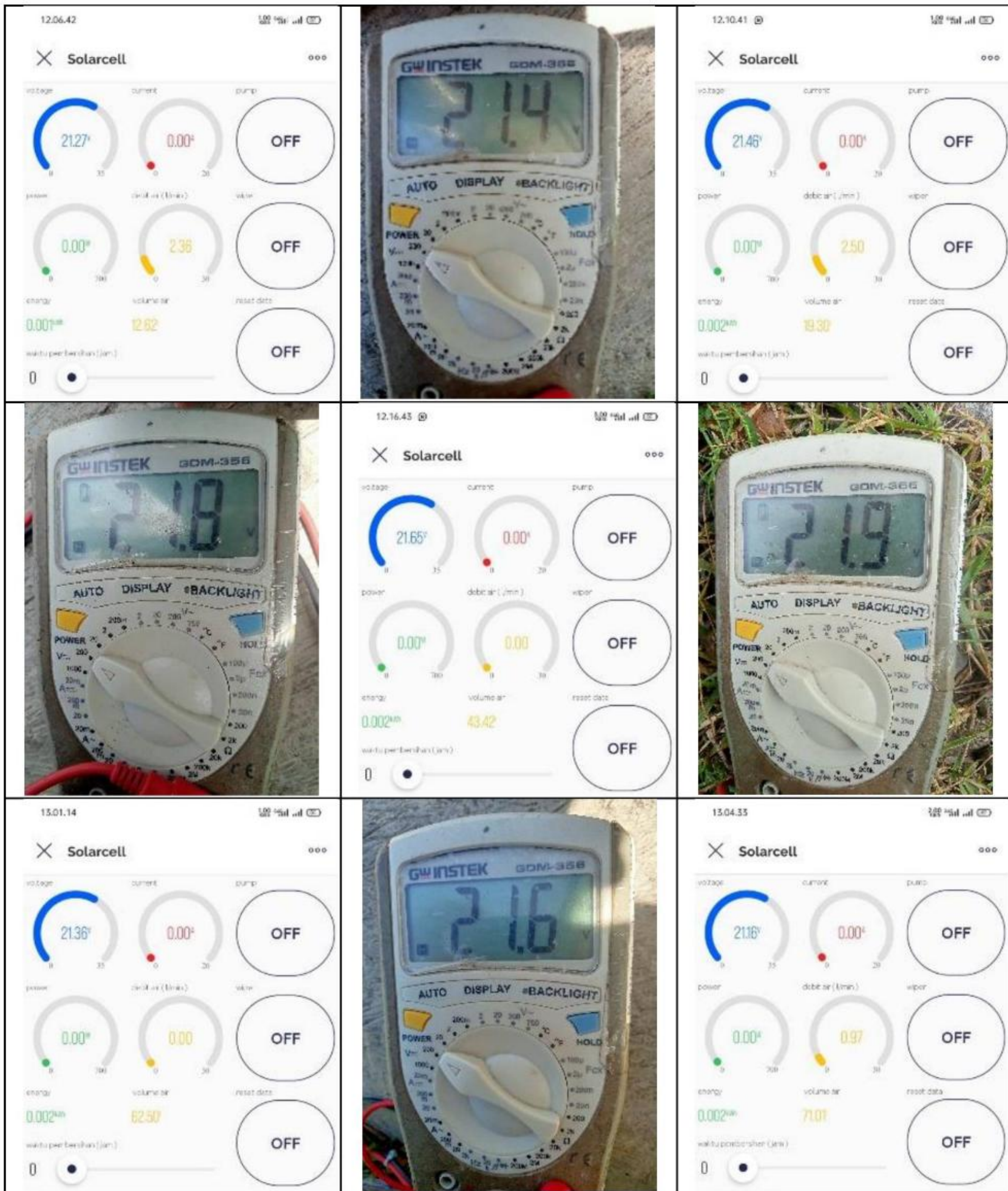
Perakitan Mekanikal		
		
		
		

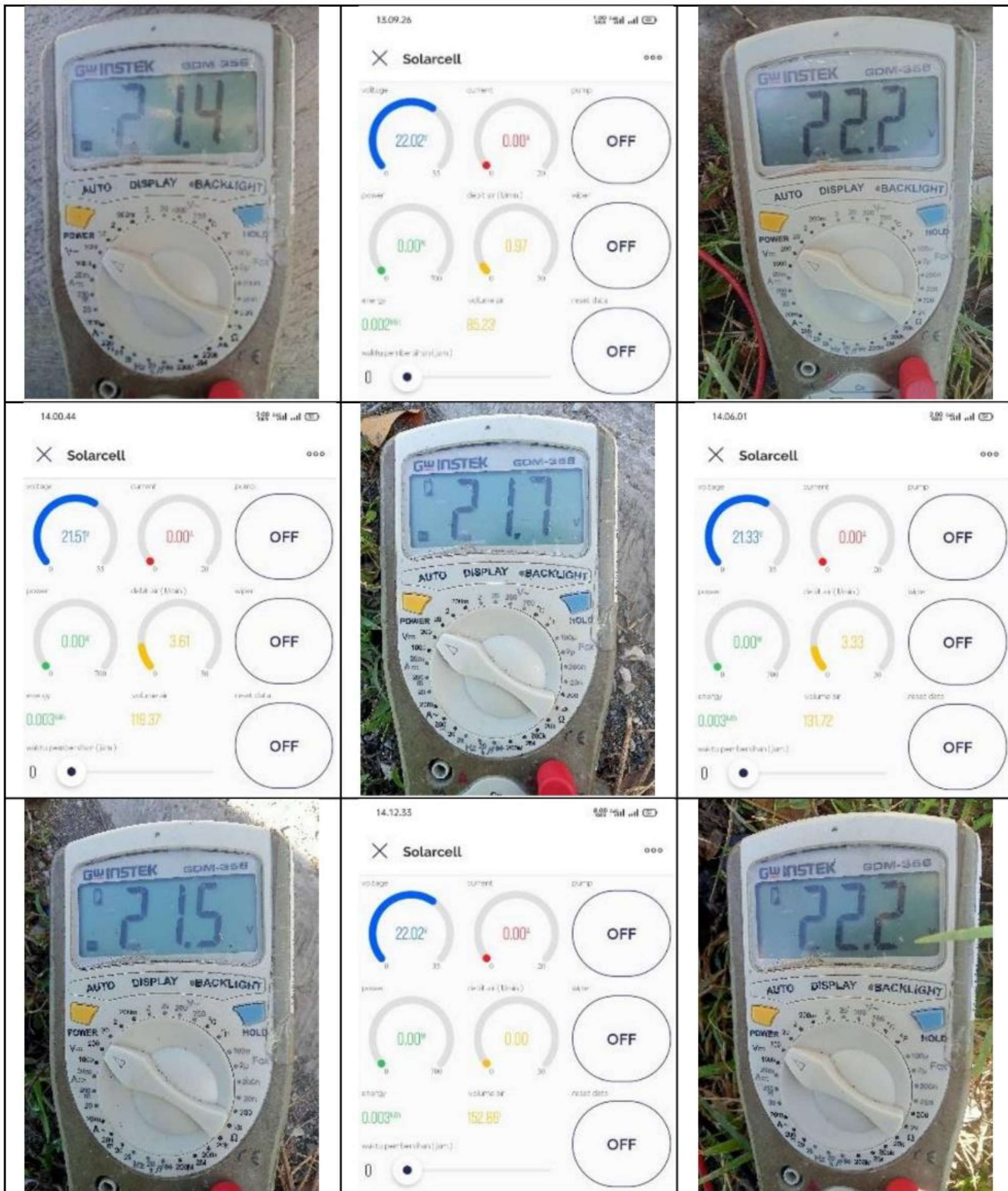
LAMPIRAN B

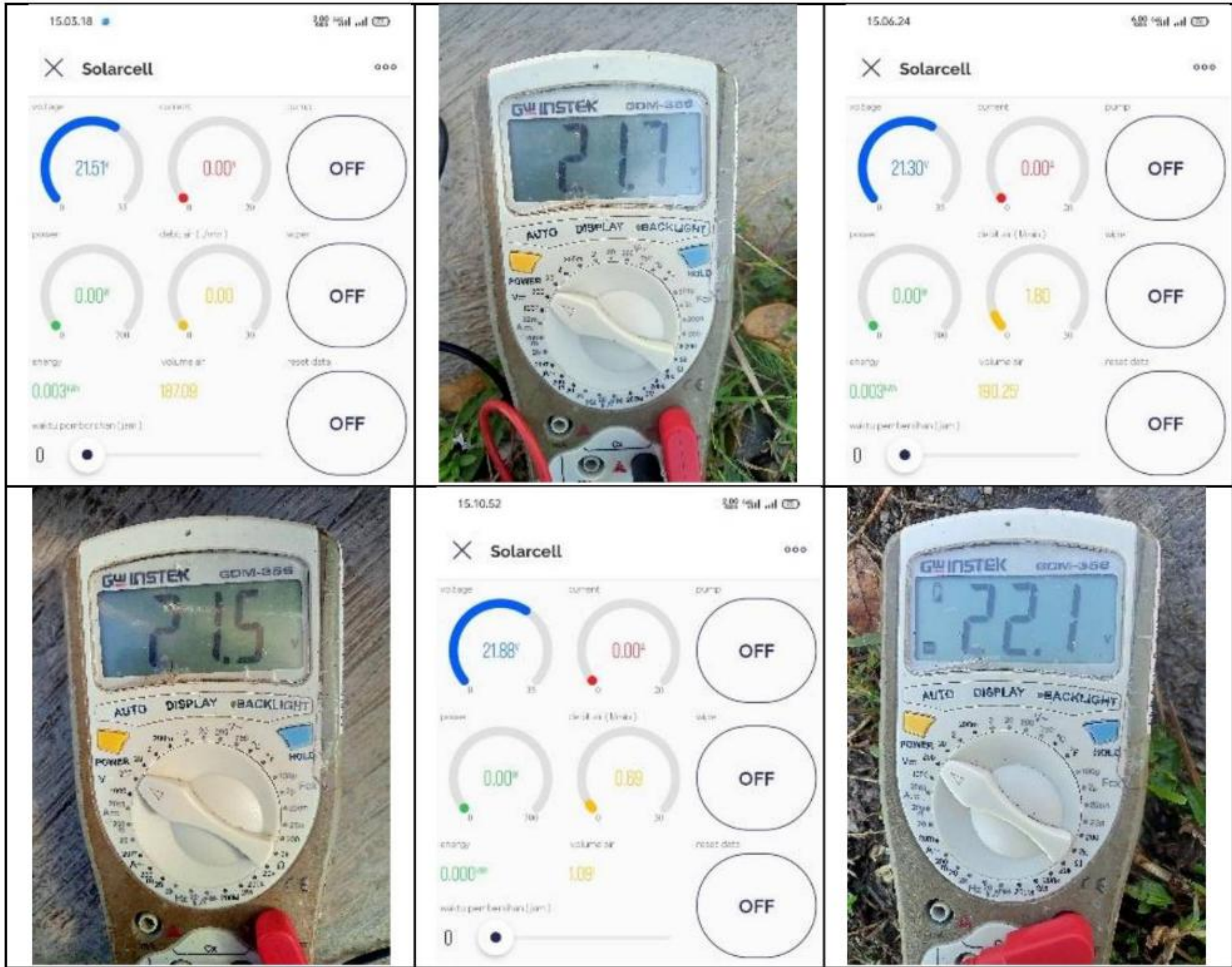
Pengambilan Data Tegangan Output Panel Surya Tanpa Beban

Pengambilan Data Pengukuran Tegangan		
		
		
		





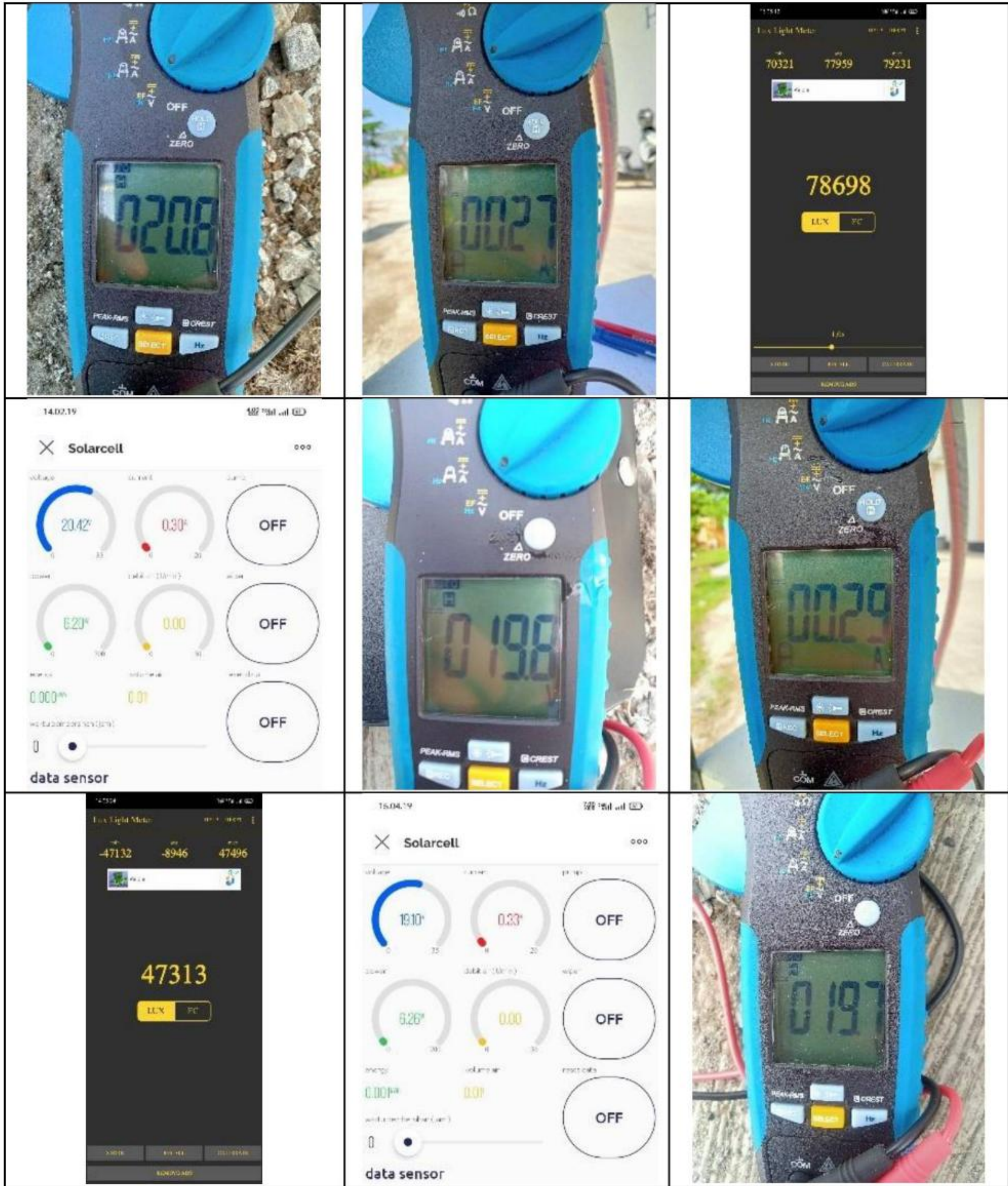




LAMPIRAN C

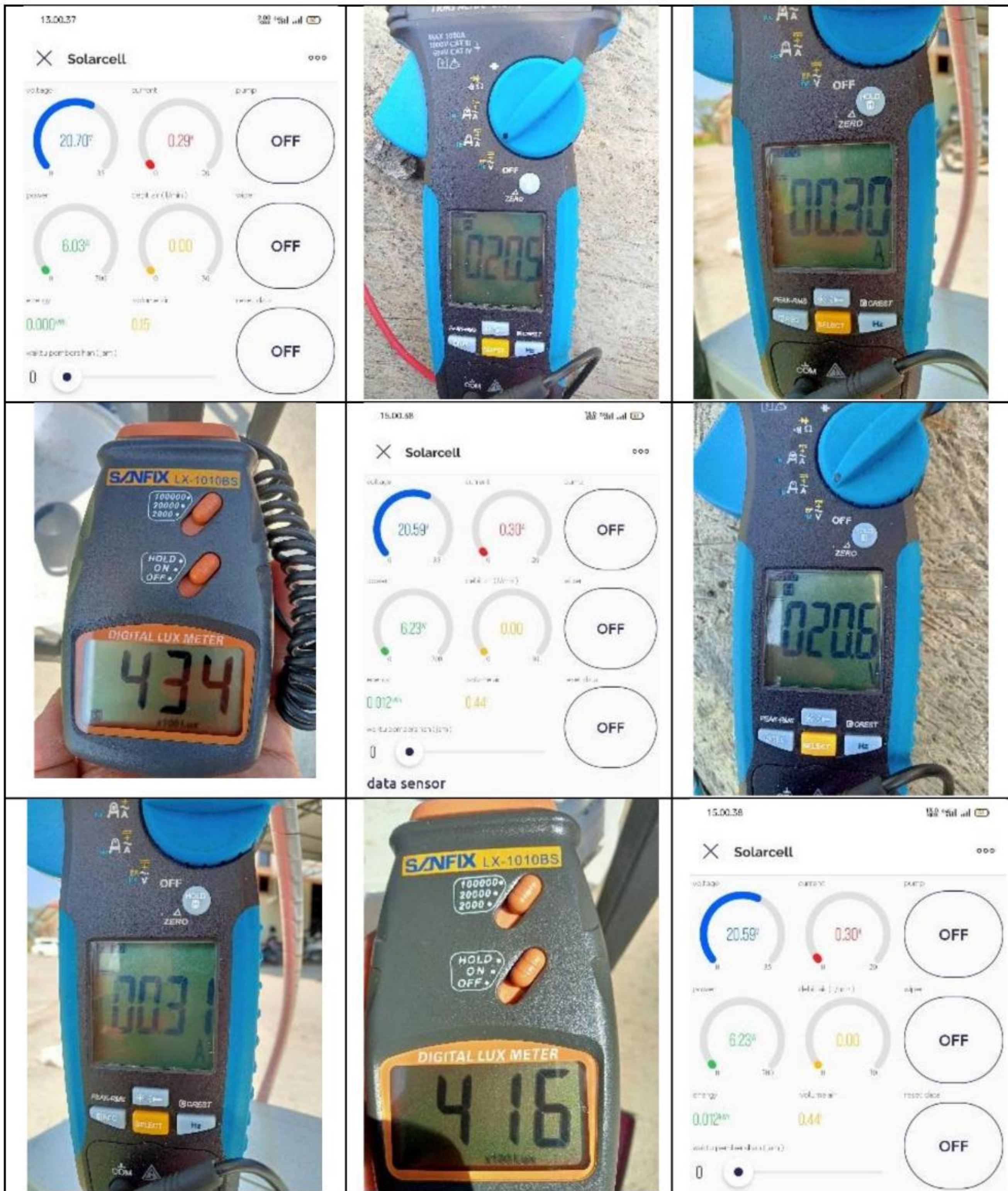
Pengambilan Data Tegangan Dan Arus Panel Surya Dengan Beban

Pengambilan Data Pengukuran Tegangan Dan Arus		
		
		
		





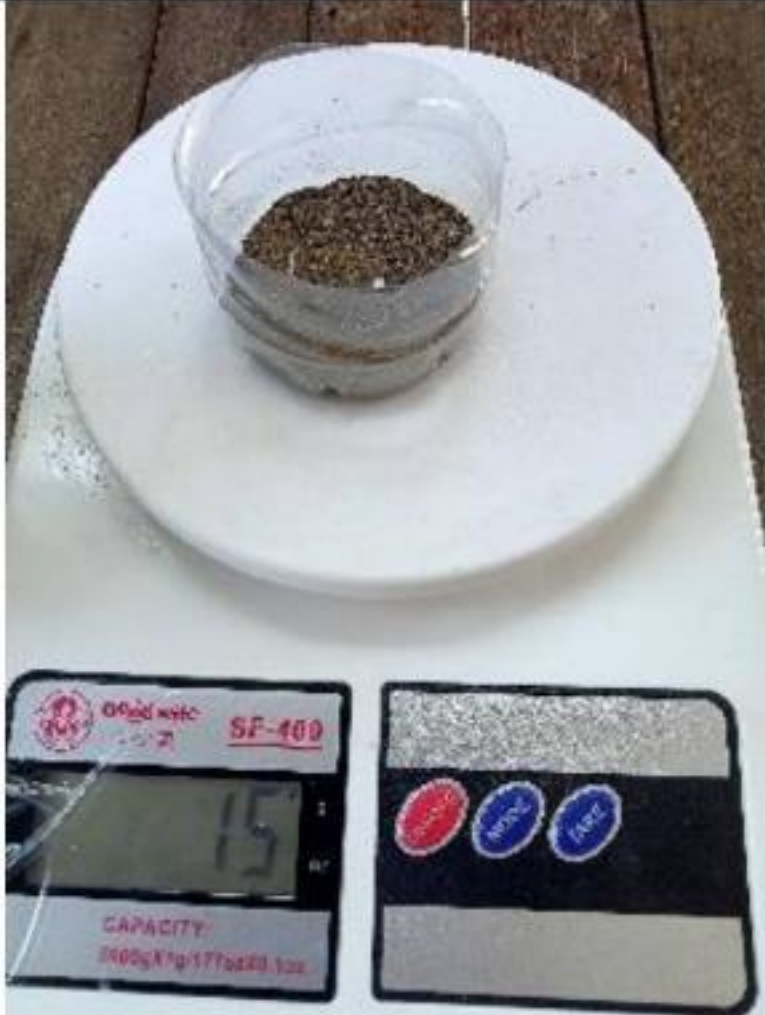
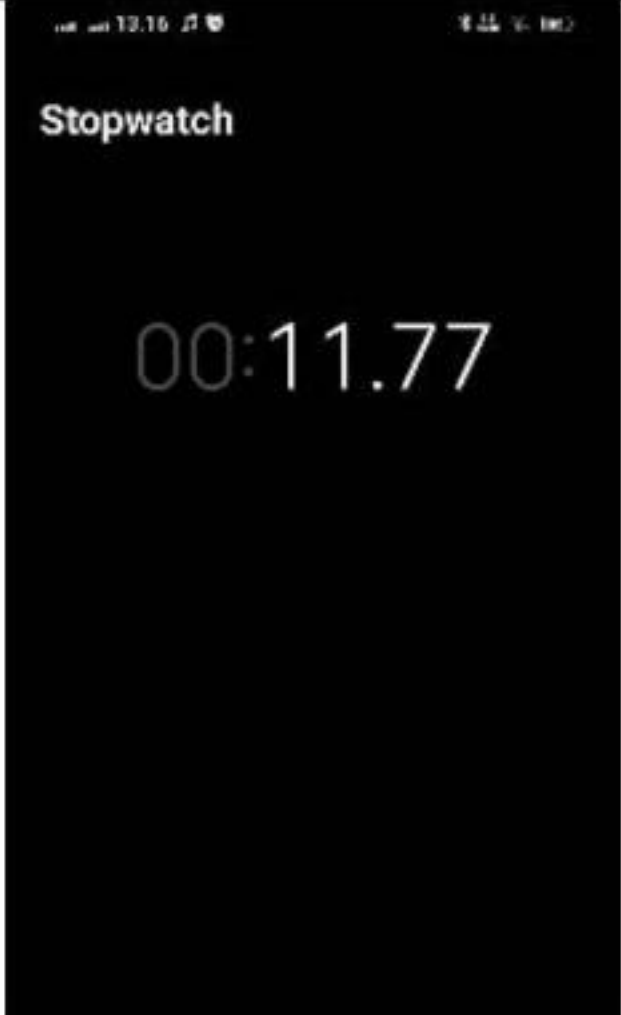


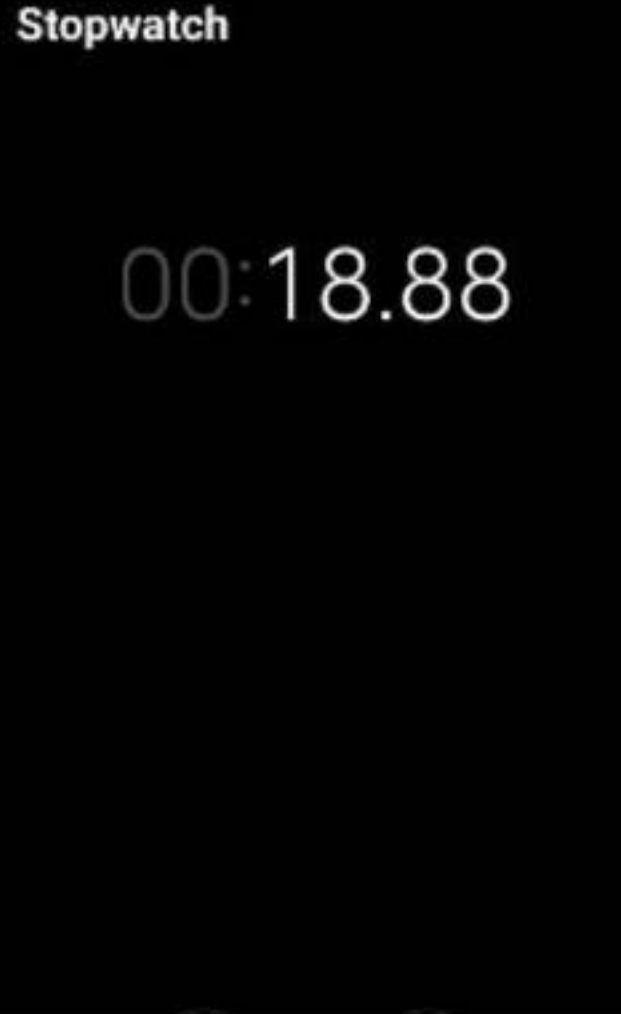


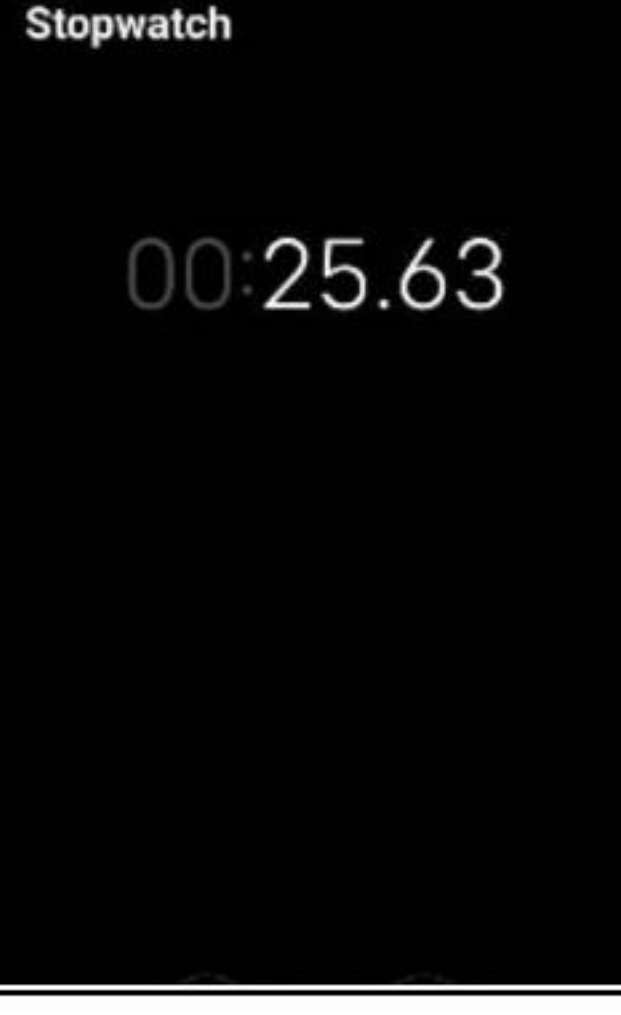



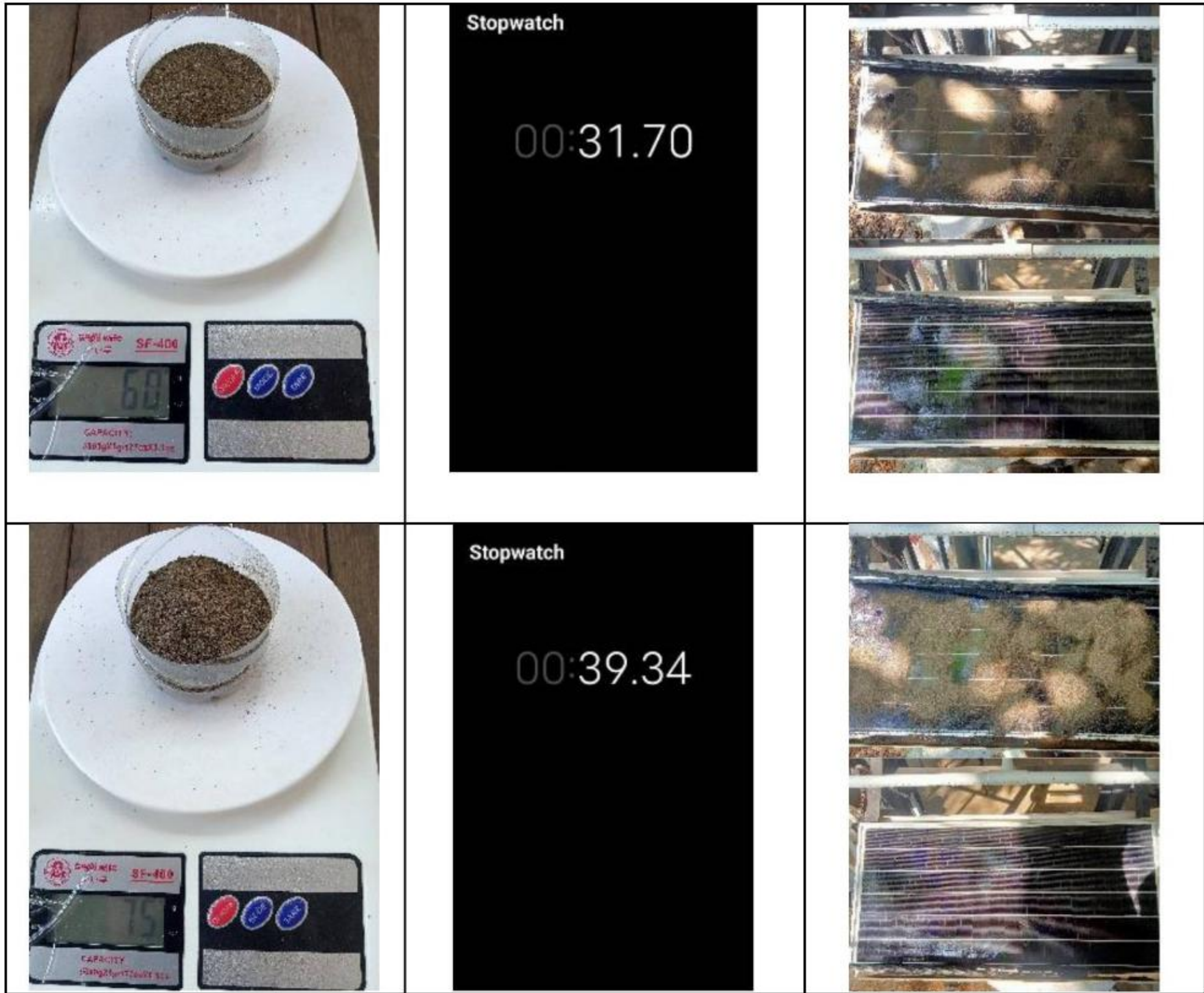




LAMPIRAN D










Pengambilan Data Pembersihan Panel Surya

Pengambilan Data Pembersihan Panel Surya		
		
		
		



LAMPIRAN E

Pengambilan Data Suhu pada Output Panel Surya

Pengambilan Data Pengukuran Suhu		
Normal	Berdebu	Dibersihkan
		
		
		

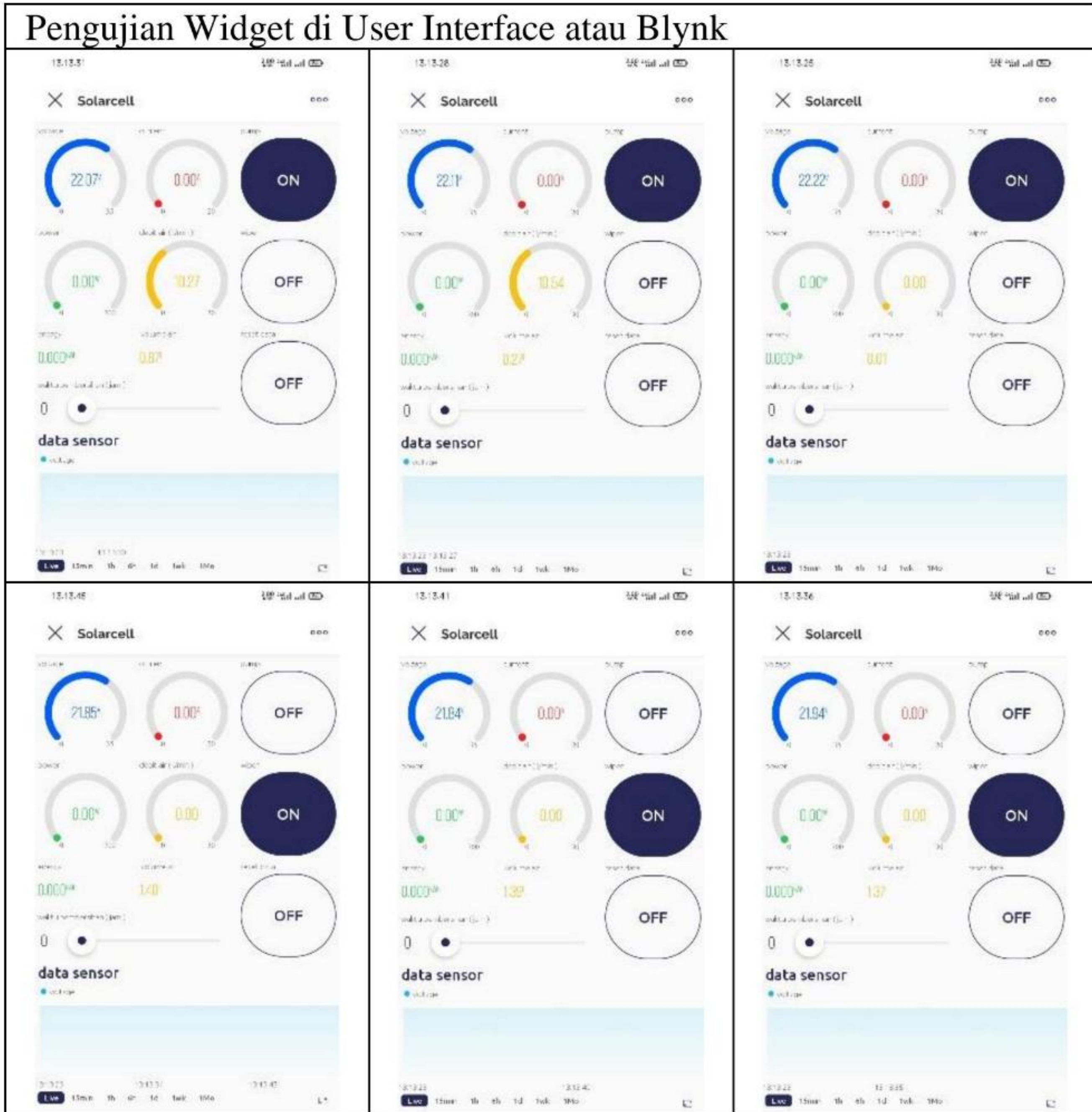


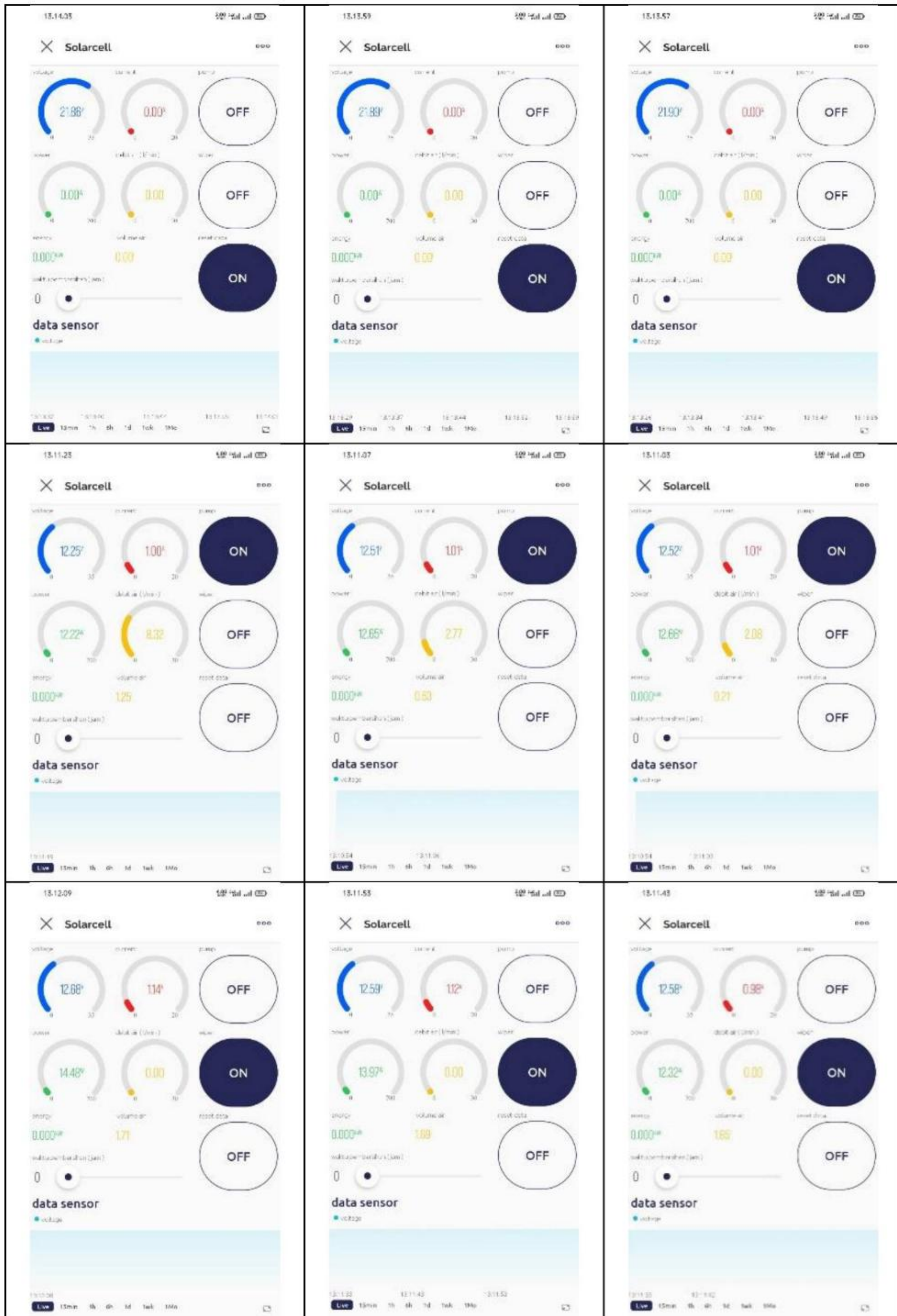
LAMPIRAN F
Pengambilan Jarak Koneksi WiFi

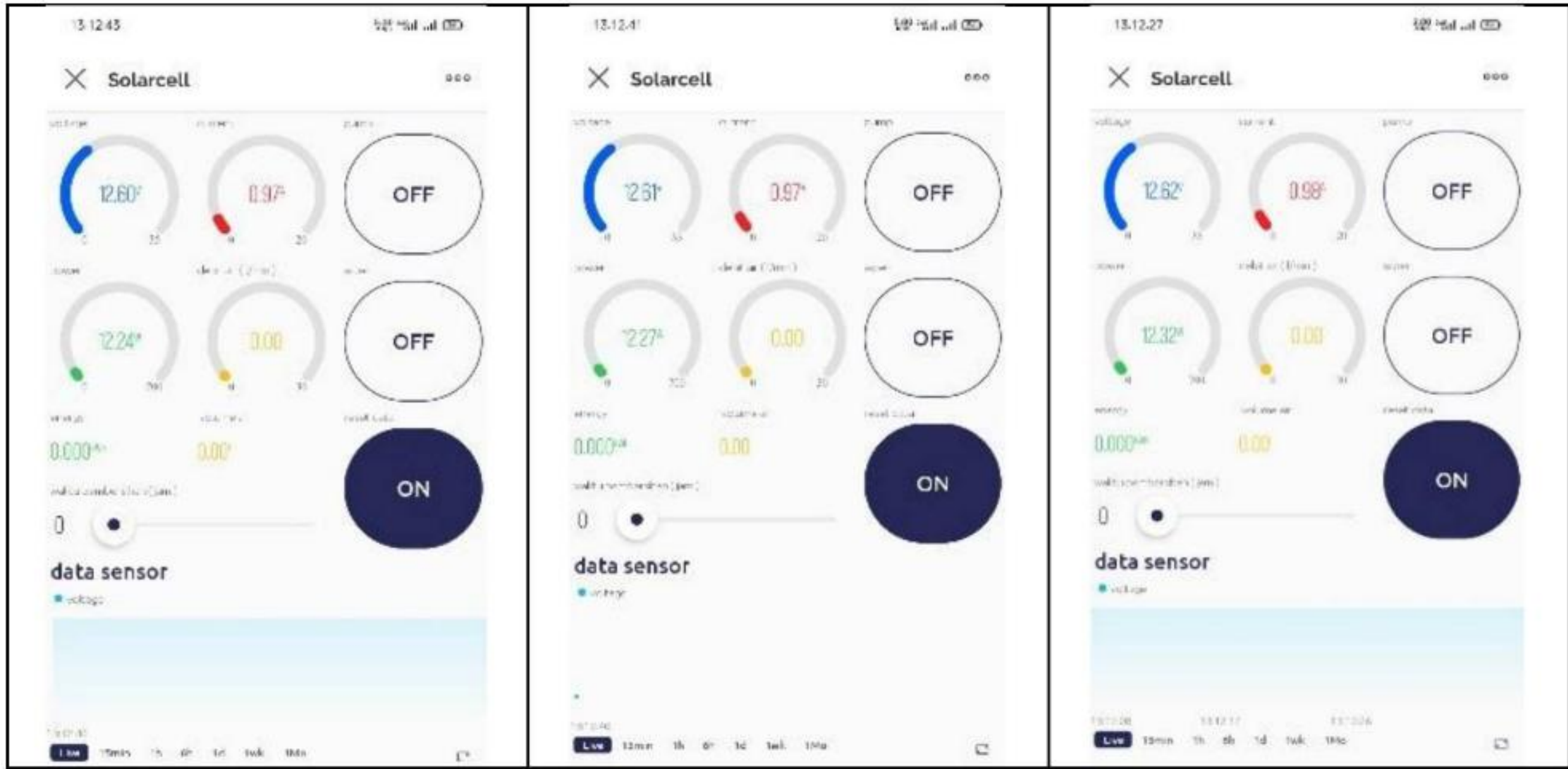


LAMPIRAN G

Pengujian Widget di User Interface

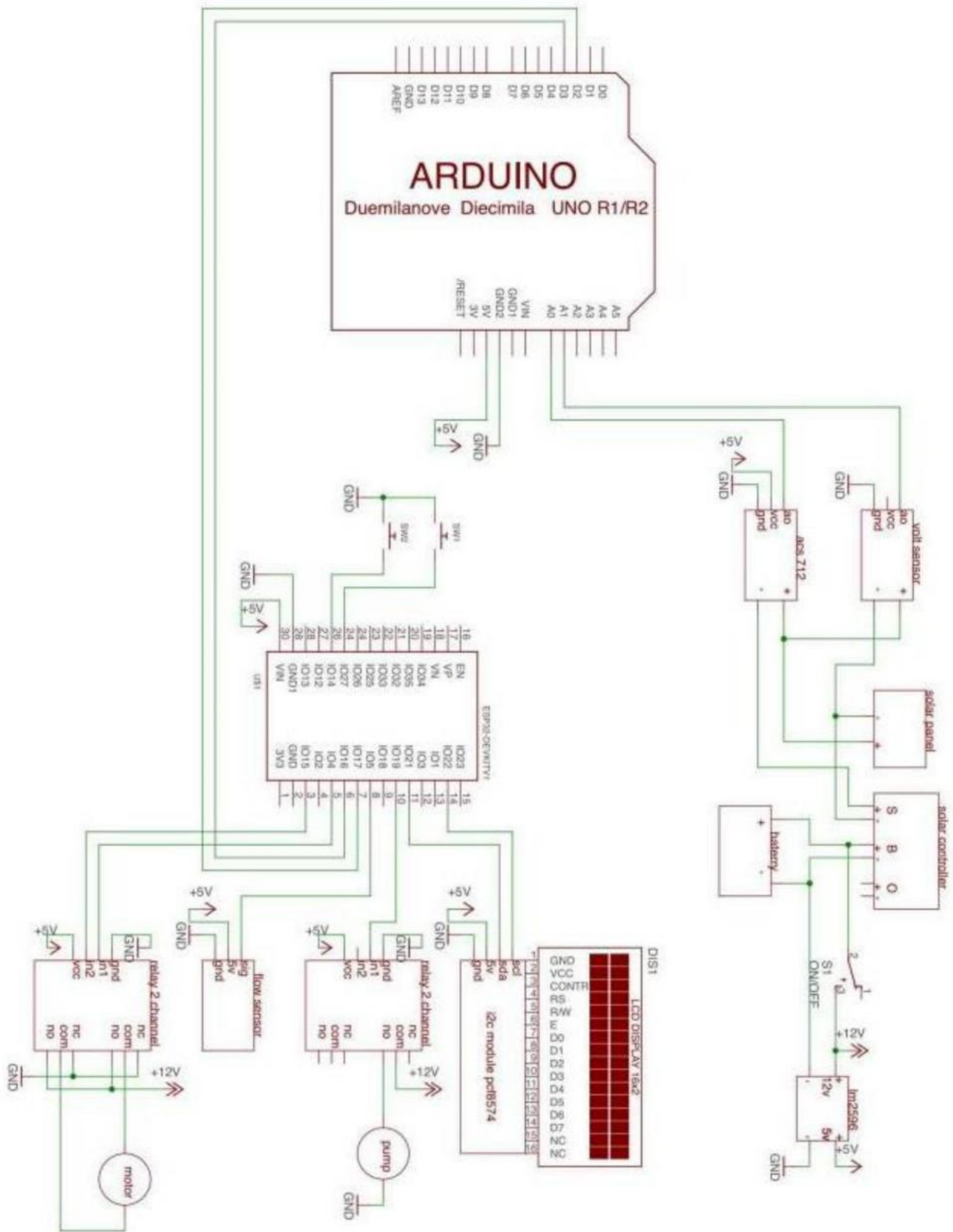






LAMPIRAN H

Wiring System



LAMPIRAN I

Program Sistem

A. Program Arduino Uno

```
#include <SoftwareSerial.h>
SoftwareSerial mySerial(2, 3); // RX, TX
#include <EEPROM.h>
#include "ACS712.h"
#define pincurrent A0
#define pinvolt A1
#define pinled 13

ACS712 sensor(ACS712_20A, pincurrent);
float current,voltage,power,energy,wh,recw=0,lwh;
float zero_factor = 0.12; // zero untuk sensor current
float factorcurrent = 1.0; // factor kalibrasi arus
float factorvoltage = 1.0; // factor kalibrasi tegangan

unsigned long previousMillis = 0;
const long interval = 1000;
int counter=0;

// referensi https://how2electronics.com/interfacing-0-25v-dc-voltage-sensor-with-arduino/

float read_voltage(int pinsensor){
float adc_voltage = 0.0;
float in_voltage = 0.0;
float R1 = 30000.0;
float R2 = 7500.0;
float ref_voltage = 5.0;
int adc_value = 0;
adc_value = analogRead(pinsensor);
adc_voltage = (adc_value * ref_voltage) / 1024.0;
in_voltage = adc_voltage / (R2/(R1+R2)) ;
return in_voltage;
}
```

```

void setup() {
recw = EEPROM.get(0, recw);
pinMode(pinled, OUTPUT);
Serial.begin(9600);
mySerial.begin(9600);
Serial.println(" ready ");
}
void loop() {
unsigned long currentMillis = millis();
if (currentMillis - previousMillis >= interval) {
previousMillis = currentMillis;

current=0;
voltage=0;
for(int i=0; i<100; i++){
current += sensor.getCurrentDC();
voltage += read_voltage(pinvolt);
delay(1);
}
current = current / 100.0;
current = (current - zero_factor)*factorcurrent;
if(current<0.0)current=0;
voltage = (voltage / 100.0)*factorvoltage;
power = current * voltage;

recw += power;
wh = recw / 3600;
energy = wh / 1000; // konvert ke kwh

if(lwh!=wh){
EEPROM.put(0, recw);
lwh=wh;
}
Serial.print(current);
Serial.print(" A ");
Serial.print(voltage);
Serial.print(" V ");
Serial.print(power);
Serial.print(" W ");

```

```
Serial.print(energy,4);  
Serial.print("K ");  
Serial.print(counter);  
Serial.print("C ");  
Serial.println();
```

```
mySerial.print(current);  
mySerial.print(" A ");  
mySerial.print(voltage);  
mySerial.print(" V ");  
mySerial.print(power);  
mySerial.print(" W ");  
mySerial.print(energy,4);  
mySerial.print("K ");  
mySerial.print(counter);  
mySerial.print("C ");  
mySerial.println();  
counter++;  
}
```

```
if(Serial.available()){  
char c=Serial.read();  
if(c=='R'){  
recw=0;  
EEPROM.put(0, recw);  
Serial.println(" reset kwh ok ");  
digitalWrite(pinled,1);  
delay(1000);  
digitalWrite(pinled,0);  
}  
}  
if(mySerial.available()){  
char cc=mySerial.read();  
if(cc=='R'){  
recw=0;  
EEPROM.put(0, recw);  
Serial.println(" reset kwh ok ");  
digitalWrite(pinled,1);  
delay(1000);
```



```
digitalWrite(pinled,0);  
}  
}  
}
```

B. Program ESP32

```
// sistemmonitoring0@gmail.com  
// Sandiku312213
```

```
#include <ESP32Servo.h>
```

```
#define pump 19  
#define rpwm 4  
#define lpwm 15  
#define flow 5  
#define rsw 14  
#define lsw 27
```

```
// token blynk
```

```
#define BLYNK_TEMPLATE_ID "TMPL6vONPVkri"  
#define BLYNK_TEMPLATE_NAME "solarcell"  
#define BLYNK_AUTH_TOKEN  
"bCKIODMUw5ttN6ckHLdyBzVkUP5DVaAS"
```

```
#define BLYNK_PRINT Serial // tampilkan informasi blynk di serial  
#include <BlynkSimpleEsp32.h> // library blynk
```

```
// input wifi dan password
```

```
char auth[] = BLYNK_AUTH_TOKEN;  
char ssid[] = "WIFI-TE1"; // type your wifi name  
char pass[] = "politeknikcilacap"; // type your wifi password  
BlynkTimer timers;
```

```
#include <NTPClient.h>
```

```
const long utcOffsetInSeconds = 25200;
```

```
// Define NTP Client to get time
```

```
WiFiUDP ntpUDP;
```

```
NTPClient timeClient(ntpUDP, "id.pool.ntp.org", utcOffsetInSeconds);
```

```
String tanggal,waktu;
```

```

int jam;

// lcd library
#include <LiquidCrystal_I2C.h>
LiquidCrystal_I2C lcd(0x27, 16, 2);

#define pinled 2

// eeprom library
#include <EEPROM.h>

int setwaktu;
float arus,tegangan,power,energy;

int count1=0,count2=0;

float konst = 7.2; // faktor kalibrasi
float debit_air;

volatile byte count;

unsigned int flow_mlt;
float total_volume,ltotal_volume;
float total_volume_liter;
unsigned long oldTime;
int laju_aliran;

String statuspump="F";
String statuswiper="S";
int startwiper=0;
String settime="";
String settime1="";
int t1,t2=15;

// external interupsi
ICACHE_RAM_ATTR void countPulse(){
  count++;
}

```

```
// membaca input dari blynk
BLYNK_WRITE(V7){
  int pinValue = param.asInt();
  setwaktu = pinValue;
  Serial.print("set waktu:");
  Serial.println(pinValue);
  EEPROM.write(0, pinValue);
  EEPROM.commit();
}
```

```
// membaca input dari blynk
BLYNK_WRITE(V5){
  int pinValue = param.asInt();
  if(pinValue==1){
    if(digitalRead(pump)==1) {
      digitalWrite(pump,0);
      statuspump="N";
    }
    else {
      digitalWrite(pump,1);
      statuspump="F";
    }
  }
  Serial.print("pump:");
  Serial.println(pinValue);
}
```

```
// membaca input dari blynk
BLYNK_WRITE(V6){
  int pinValue = param.asInt();
  if(pinValue == 1){
    if(startwiper==0) {
      startwiper=1;
      if(digitalRead(rsw)==0) {digitalWrite(rpwm, 0);digitalWrite(lpwm,
1);statuswiper="R";}
      if(digitalRead(lsw)==0) {digitalWrite(rpwm, 1);digitalWrite(lpwm,
0);statuswiper="L";}
    }
  }
}
```

```

if(digitalRead(rsw)==1 &&digitalRead(lsw)==1) {digitalWrite(rpwm,
0);digitalWrite(lpwm, 1);statuswiper="R";}
}
else {
startwiper=0;
digitalWrite(rpwm, 1);digitalWrite(lpwm, 1);
}
}
Serial.print("wiper:");
Serial.println(pinValue);
}

```

```

// membaca input dari blynk
BLYNK_WRITE(V8){
int pinValue = param.asInt();
if(pinValue==1){
total_volume=0;
EEPROM.put(10, total_volume);
EEPROM.commit();
Serial2.print("R");
Serial.println("reset ok");
}
Serial.print("reset:");
Serial.println(pinValue);
}

```

```

void get_time(){
timeClient.update();
unsigned long epochTime = timeClient.getEpochTime();
struct tm *ptm = gmtime ((time_t *)&epochTime);
int monthDay = ptm->tm_mday;
int currentMonth = ptm->tm_mon+1;
int currentYear = ptm->tm_year+1900;
tanggal=String(monthDay);
tanggal+="-";
tanggal+=String(currentMonth);
tanggal+="-";
tanggal+=String(currentYear);
}

```

```

jam = timeClient.getHours();
waktu = timeClient.getFormattedTime();
Serial.println(tanggal);
Serial.println(waktu);
Serial.println(jam);
}

```

```

void display_lcd(){
  count1++;
  if( count1 >=5 ){count1=0;count2++;}
  if(count2>2)count2=0;
  if(count2==0){
    lcd.clear();
    lcd.setCursor(0,0);
    lcd.print(arus);
    lcd.print(" A");
    lcd.setCursor(13,0);
    lcd.print("P:");
    lcd.print(statuspump);

```

```

    lcd.setCursor(0,1);
    lcd.print(tegangan);
    lcd.print(" V");
    lcd.setCursor(13,1);
    if(startwiper==0) lcd.print("W:");
    else lcd.print("w:");
    lcd.print(statuswiper);
  }

```

```

  if(count2==1){
    lcd.clear();
    lcd.setCursor(0,0);
    lcd.print(power);
    lcd.print(" W");
    lcd.setCursor(13,0);
    lcd.print("P:");
    lcd.print(statuspump);

```

```

    lcd.setCursor(0,1);
    lcd.print(energy,3);

```

```
lcd.print("kWh");  
lcd.setCursor(13,1);  
if(startwiper==0) lcd.print("W:");  
else lcd.print("w:");  
lcd.print(statuswiper);  
}  
if(count2==2){  
lcd.clear();  
lcd.setCursor(0,0);  
lcd.print(debit_air);  
lcd.print("L/m");  
lcd.setCursor(13,0);  
lcd.print("P:");  
lcd.print(statuspump);
```

```
lcd.setCursor(0,1);  
lcd.print(total_volume_liter);  
lcd.print("L");  
lcd.setCursor(13,1);  
if(startwiper==0) lcd.print("W:");  
else lcd.print("w:");  
lcd.print(statuswiper);  
}
```

```
if(count2==2){  
lcd.clear();  
lcd.setCursor(0,0);  
lcd.print("T:");  
lcd.print(waktu);
```

```
lcd.setCursor(13,0);  
lcd.print("P:");  
lcd.print(statuspump);
```

```
lcd.setCursor(0,1);  
lcd.print("D:");  
lcd.print(tanggal);
```

```
lcd.setCursor(13,1);
```

```

if(startwiper==0) lcd.print("W:");
else lcd.print("w:");
lcd.print(statuswiper);
}
}

// update ke blynk dan tampilan blynk
void tasktimer(){

if(setwaktu==jam){
if(t1<t2){
if(t1==0)Blynk.logEvent("notifications","Wiper dan pompa Nyala
otomatis!");
startwiper=1;
if(digitalRead(rsw)==0) {digitalWrite(rpwm, 0);digitalWrite(lpwm,
1);statuswiper="R";}
if(digitalRead(lsw)==0) {digitalWrite(rpwm, 1);digitalWrite(lpwm,
0);statuswiper="L";}
if(digitalRead(rsw)==1&&digitalRead(lsw)==1) {digitalWrite(rpwm,
0);digitalWrite(lpwm, 1);statuswiper="R";}
digitalWrite(pump,0);
statuspump="N";
Serial.println("saatnya on");
}
else{
if(t1==t2)Blynk.logEvent("notifications","Wiper dan pompa Mati
otomatis!");
startwiper=0;
digitalWrite(rpwm, 1);digitalWrite(lpwm, 1);
statuswiper="S";
digitalWrite(pump,1);
statuspump="N";
Serial.println("saatnya on");
}
t1++;
}
else{
t1=0;
}
}
}

```

```

}

// menampilkan di blynk
Blynk.virtualWrite(V0,tegangan);
Blynk.virtualWrite(V1,arus);
Blynk.virtualWrite(V2,power);
Blynk.virtualWrite(V3,energy);
Blynk.virtualWrite(V4,total_volume_liter);
Blynk.virtualWrite(V9,debit_air);

display_lcd();

}

// fungsi setup hanya di run sekali saat esp pertama on
// gunanya untuk inialisasi / konfigurari input output
void setup(){
  Serial.begin(9600);
  Serial2.begin(9600);
  // konfigurasi eeprom
  EEPROM.begin(512);
  // baca memory dr eeprom
  setwaktu = EEPROM.read(0);
  Serial.print("setwaktu:");
  Serial.println(setwaktu);
  total_volume = EEPROM.get(10, total_volume);
  Serial.print("ml:");
  Serial.println(total_volume);
  pinMode(pinled, OUTPUT);
  pinMode(pump, OUTPUT);
  digitalWrite(pump, 1); // off
  pinMode(lpwm, OUTPUT);
  pinMode(rpwm, OUTPUT);
  digitalWrite(rpwm, 1);digitalWrite(lpwm, 1);
  pinMode(flow, INPUT_PULLUP);
  pinMode(rsw, INPUT_PULLUP);
  pinMode(lsw, INPUT_PULLUP);

  ESP32PWM::allocateTimer(0);

```



```

ESP32PWM::allocateTimer(1);
ESP32PWM::allocateTimer(2);
ESP32PWM::allocateTimer(3);

lcd.begin();
lcd.backlight();
// tampilan awal lcd
lcd.clear();
lcd.setCursor(0,0);
lcd.print("ssid:");
lcd.print(ssid);
lcd.setCursor(0,1);
lcd.print("pass:");
lcd.print(pass);

// inisialisasi blynk
Blynk.begin(auth, ssid, pass);
timers.setInterval(1000L, tasktimer);

count = 0;
debit_air = 0.0;
flow_mlt = 0;

oldTime = 0;

attachInterrupt(digitalPinToInterrupt(flow), countPulse, FALLING);
Serial.println(" ready ");
timeClient.begin();
}

String in="";
void loop()
{

if(startwiper==1){
if(digitalRead(rsw)==0) {digitalWrite(rpwm, 0);digitalWrite(lpwm,
1);statuswiper="R";}

```

```
if(digitalRead(lsw)==0) {digitalWrite(rpwm, 1);digitalWrite(lpwm,  
0);statuswiper="L";}  
}
```

```
Blynk.run(); // jalankan blynk  
timers.run(); // jalankan timer
```

```
if(Serial2.available()){  
char c = Serial2.read();  
if(isDigit(c)||c=='.'||c=='-')in+=c;  
if(c==' ')in="";  
if(c=='A'){  
arus= in.toFloat();  
Serial.print(in);  
Serial.print("a ");  
in="";  
}  
if(c=='V'){  
tegangan = in.toFloat();  
Serial.print(in);  
Serial.print("v ");  
in="";  
}  
if(c=='W'){  
power = in.toFloat();  
Serial.print(in);  
Serial.print("w ");  
in="";  
}  
if(c=='K'){  
energy = in.toFloat();  
Serial.print(in);  
Serial.print("kwh ");  
Serial.println();  
in="";  
}  
}
```

```
if ((millis() - oldTime) > 1000) {
```

```

detachInterrupt(0);
debit_air = ((1000.0 / (millis() - oldTime)) * count) / konst;
oldTime = millis();
flow_mlt = (debit_air / 60) * 1000;
total_volume += flow_mlt;
laju_aliran = debit_air;

total_volume_liter = (float)total_volume/1000;

Serial.print("S1:");
Serial.print(digitalRead(rsw));
Serial.print(" S2:");
Serial.print(digitalRead(lsw));

Serial.print(" DEBIT AIR: ");
Serial.print(debit_air);
Serial.print("L/m");
Serial.print(" Vol: ");
Serial.print(total_volume);
Serial.print("mL");
Serial.print(" Vol: ");
Serial.print(total_volume_liter);
Serial.println("L");

if(!total_volume!=total_volume){
  EEPROM.put(10, total_volume);
  EEPROM.commit();
  ltotal_volume=total_volume;
}
get_time();
count = 0;
digitalWrite(pinled, digitalRead(pinled)^1);
attachInterrupt(0, countPulse, FALLING);
}
}

```