

LAMPIRAN A

Program

```
#include <PZEM004Tv30.h>

#include <Wire.h>

#include <LiquidCrystal_I2C.h>

#include <WiFi.h>

#include <FirebaseESP32.h>

#include <addons/TokenHelper.h>

#include <addons/RTDBHelper.h>

#define WIFI_SSID "inuy"

#define WIFI_PASSWORD "00000000"

#define API_KEY
"AIzaSyCBPQ8BaAm4IKyKJQPKDNxhZgnPPTos1k8"

#define DATABASE_URL "https://inuyuni1105-default-
rtdb.firebaseio.com"

#define USER_EMAIL "inuyunierawati23@gmail.com"

#define USER_PASSWORD "politeknikcilacap23"

#if !defined(PZEM_RX_PIN) && !defined(PZEM_TX_PIN)

#define PZEM_RX_PIN 16

#define PZEM_TX_PIN 17

#endif

#if !defined(PZEM_SERIAL
```

```
#define PZEM_SERIAL Serial2

#endif

#if defined(ESP32)

PZEM004Tv30      pzem(PZEM_SERIAL,      PZEM_RX_PIN,
PZEM_TX_PIN);

#elif defined(ESP8266)

#else

PZEM004Tv30 pzem(PZEM_SERIAL);

#endif

#define cap10 26

#define cap5 27

#define cap3 13

unsigned long timeShow = 0;

unsigned long prefMilis;

byte flagRun;

double s , q_sebelum , q_setelah , kebutuhan , capasitor , micro_farad ;

double xc;

double qc;
```

```
double tg_sudut;

float v, i, w, e, f, pf;

float v0, i0, w0, e0, f0, pf0;

float v1, i1, w1, e1, f1, pf1;

float ss, setelah, hasil;

float c_hasil;

float pf_setelah;

float pf_sebelum;

int counter;

unsigned long backTimer;

bool signupOK = false;

FirebaseData fbdo;

FirebaseAuth auth;

FirebaseConfig config;

LiquidCrystal_I2C lcd(0x27, 20, 4);

void setup() {

    Serial.begin(9600);

    lcd.begin();

    firebaseInitial();

    pinMode(cap10, OUTPUT);

    pinMode(cap5, OUTPUT);
```

```

pinMode(cap3, OUTPUT);
digitalWrite(cap10, LOW);
digitalWrite(cap5, LOW);
digitalWrite(cap3, LOW);
// delay(1000);
// digitalWrite(cap1, HIGH);
// delay(1000);
// digitalWrite(cap1, LOW);
}
void loop() {
  pzemRead();
  showLcd();
  // logicAll();
  logicNew();
  rumusJLL();
  if ((millis() - prefMilis) > 1000) {
    Serial.println("voll= " + String(v) + " ");
    Serial.println("current= " + String(i) + " ");
    Serial.println("watt= " + String(w) + " ");
    Serial.println("energy= " + String(e) + " ");
    Serial.println("frek= " + String(f) + " ");
  }
}

```

```

Serial.println("pf= " + String(pf) + " ");

Serial.println("_____");

prefMilis = millis();
}

firebaseSendData();
}

void pzemRead() {
  v = pzem.voltage(), 2;
  i = pzem.current(), 2;
  w = pzem.power(), 2 ;
  e = pzem.energy(), 2;
  f = pzem.frequency(), 2;
  pf = pzem.pf();
}

void rumus() {
  s = v * i;

  q_sebelum = w * (tan(acos (pf)));
  q_setelah = w * (tan(acos (0.98)));
  kebutuhan = q_sebelum - q_setelah;
  capasitor = (kebutuhan * 1000) / (((3.14 * 3.14) * f) * (v * v));
  micro_farad = (capasitor * 1000000) / 1000;
}

```

```

xc = 1 / (2 * 3.14 * f * micro_farad);
qc = (v * v) / xc;
tg_sudut = qc / w;
setelah = atan(tg_sudut);
ss = sqrt((kebutuhan * kebutuhan) + (w * w));
hasil = (w / ss);
}
void rumusJIL() {
//Rumus S
s = v * i;
float radarcos1 = (pf * 3.14) / 180;
float rad1 = acos((radarcos1) * 180 / 3.14);
float Arccos1 = rad1 * 57.3;
// Rumus Q1
float radsin = (Arccos1 * 3.14) / 180;
float Sin = sin(radsin);
float Q1 = v * i * Sin;
//Rumus Arccos 2
float phi2 = 0.98;
float radarcos2 = (phi2 * 3.14) / 180;

```

```

float rad2 = acos((radarcos2) * 180 / 3.14);
float Arccos2 = rad2 * 57.3;

// Rumus Q
float radtan = (Arccos2 * 3.14) / 180;
float Tan = tan(radtan);
float Q = w * Tan;

// Rumus Q2
float Q2 = Q1 - Q;

//Rumus Z
float Z = pow(v, 2) / Q2;
float C = (1 / (2 * 3.14 * 50 * Z)) * 1000000;
if (C < 0) {
    C = C * -1;
}
else {
    C = C;
}
c_hasil = C;
}

void showLcd() {

```

```
if (millis() - timeShow > 2000) {  
    lcd.clear();  
    flagRun++;  
    timeShow = millis();  
}  
switch (flagRun) {  
    case 0:  
        break;  
    case 1:  
        lcd.setCursor(10, 0);  
        lcd.print("READING ");  
        lcd.setCursor(10, 1);  
        lcd.print("AKTUAL ");  
        lcd.setCursor(0, 0);  
        lcd.print("V=   |");  
        lcd.setCursor(2, 0);  
        lcd.print(v);  
        lcd.setCursor(0, 1);  
        lcd.print("I=   |");  
        lcd.setCursor(2, 1);  
        lcd.print(i);
```



```
lcd.setCursor(0, 2);  
lcd.print("F=   |");  
lcd.setCursor(2, 2);  
lcd.print(f);
```

```
lcd.setCursor(0, 3);  
lcd.print("Pf=   |");  
lcd.setCursor(3, 3);  
lcd.print(pf);
```

```
lcd.setCursor(10, 2);  
lcd.print("E=   ");  
lcd.setCursor(12, 2);  
lcd.print(e);
```

```
lcd.setCursor(10, 3);  
lcd.print("P=   ");  
lcd.setCursor(12, 3);  
lcd.print(w);
```

```
break;
```

case 2:

```
lcd.setCursor(0, 0);  
lcd.print(" KEBUTUHAN CAPASITOR");  
lcd.setCursor(2, 2);  
lcd.print(String(c_hasil) + "uF ");  
break;
```

case 4:

```
lcd.setCursor(0, 0);  
lcd.print("  pf_sebelum  ");  
lcd.setCursor(2, 2);  
lcd.print(String(pf_sebelum) );  
break;
```

case 5:

```
lcd.setCursor(0, 0);  
lcd.print("  pf_setelah  ");  
lcd.setCursor(2, 2);  
lcd.print(String(pf_setelah) );  
break;
```

case 6:

```
lcd.setCursor(0, 0);
```

```

    lcd.print(" ---Wait a moment---");

    lcd.setCursor(0, 1);

    lcd.print("  SENDING DATA  ");

    lcd.setCursor(0, 2);

    lcd.print("   TO FIREBASE   ");

    break;

case 7:

    flagRun = 1;

    break;

}

}

void logicNew() {

    // if(c_hasil <= 0 ) {

    //   digitalWrite(cap10, LOW);

    //   digitalWrite(cap5, LOW);

    //   digitalWrite(cap3, LOW);

    //   pf_sebelum = pf;

    // }

    if (c_hasil >= 1.0 and c_hasil <= 3.0) {

        if (i <= 0) {

```

```

digitalWrite(cap10, LOW);
digitalWrite(cap5, LOW);
digitalWrite(cap3, LOW);
pf_sebelum = 0;
pf_setelah = 0;
}
else {
    digitalWrite(cap10, LOW);
    digitalWrite(cap5, LOW);
    digitalWrite(cap3, HIGH);
    pf_setelah = pzem.pf() + (0.98 - pzem.pf());
}
}
else if (c_hasil > 3.0 and c_hasil <= 5.0) {
    if (i <= 0) {
        digitalWrite(cap10, LOW);
        digitalWrite(cap5, LOW);
        digitalWrite(cap3, LOW);
        pf_sebelum = 0;
        pf_setelah = 0;
    }
}

```

```

else {
    digitalWrite(cap10, LOW);
    digitalWrite(cap5, HIGH);
    digitalWrite(cap3, LOW);
    pf_setelah = pzem.pf() + (0.98 - pzem.pf());
}
}
else if (c_hasil > 5.0 and c_hasil <= 8.0) {
    if (i <= 0) {
        digitalWrite(cap10, LOW);
        digitalWrite(cap5, LOW);
        digitalWrite(cap3, LOW);
        pf_sebelum = 0;
        pf_setelah = 0;
    }
    else {
        digitalWrite(cap10, LOW);
        digitalWrite(cap5, HIGH);
        digitalWrite(cap3, HIGH);
        pf_setelah = pzem.pf() + (0.98 - pzem.pf());
    }
}

```

```

}
else if (c_hasil > 8.0 and c_hasil <= 10.0) {
  if (i <= 0) {
    digitalWrite(cap10, LOW);
    digitalWrite(cap5, LOW);
    digitalWrite(cap3, LOW);
    pf_sebelum = 0;
    pf_setelah = 0;
  }
  else {
    digitalWrite(cap10, HIGH);
    digitalWrite(cap5, LOW);
    digitalWrite(cap3, LOW);
    pf_setelah = pzem.pf() + (0.98 - pzem.pf());
  }
}
else if (c_hasil > 10.0 and c_hasil <= 13.0) {
  if (i <= 0) {
    digitalWrite(cap10, LOW);
    digitalWrite(cap5, LOW);

```

```

digitalWrite(cap3, LOW);

pf_sebelum = 0;

pf_setelah = 0;

}

else {

digitalWrite(cap10, HIGH);

digitalWrite(cap5, LOW);

digitalWrite(cap3, HIGH);

pf_setelah = pzem.pf() + (0.98 - pzem.pf());

}

}

else if (c_hasil > 13.0 and c_hasil <= 15.0) {

if (i <= 0) {

digitalWrite(cap10, LOW);

digitalWrite(cap5, LOW);

digitalWrite(cap3, LOW);

pf_sebelum = 0;

pf_setelah = 0;

}

else {

digitalWrite(cap10, HIGH);

```

```

    digitalWrite(cap5, HIGH);
    digitalWrite(cap3, LOW);
    pf_setelah = pzem.pf() + (0.98 - pzem.pf());
}

}

else if (c_hasil > 15.0 and c_hasil <= 18.0) {
    if (i <= 0) {
        digitalWrite(cap10, LOW);
        digitalWrite(cap5, LOW);
        digitalWrite(cap3, LOW);
        pf_sebelum = 0;
        pf_setelah = 0;
    }
    else {
        digitalWrite(cap10, HIGH);
        digitalWrite(cap5, HIGH);
        digitalWrite(cap3, HIGH);
        pf_setelah = pzem.pf() + (0.98 - pzem.pf());
    }
}

```



```

}
else if ( c_hasil > 18.0) {
    if (i <= 0) {
        digitalWrite(cap10, LOW);
        digitalWrite(cap5, LOW);
        digitalWrite(cap3, LOW);
        pf_sebelum = 0;
        pf_setelah = 0;
    }
    else {
        digitalWrite(cap10, HIGH);
        digitalWrite(cap5, HIGH);
        digitalWrite(cap3, HIGH);
        pf_setelah = pzem.pf() + (0.98 - pzem.pf());
    }
}
else {
    digitalWrite(cap10, LOW);
    digitalWrite(cap5, LOW);
    digitalWrite(cap3, LOW);
    pf_sebelum = pf;
}

```

```

    }
}

//void logicAll() {
//
// if (pf_sebelum >= 0.01 and pf_sebelum <= 0.12) {
//   if (i <= 0) {
//     digitalWrite(cap20, LOW);
//     digitalWrite(cap10, LOW);
//     digitalWrite(cap5, LOW);
//     pf_sebelum = 0;
//     pf_setelah = 0;
//   }
//   else {
//     digitalWrite(cap20, HIGH);
//     digitalWrite(cap10, HIGH);
//     digitalWrite(cap5, HIGH);
//     pf_setelah = pzem.pf() + (0.98 - pzem.pf());
//     Serial.println("35uf");
//   }
// }
}

```

```

// else if (pf_sebelum >= 0.13 and pf_sebelum <= 0.25) {
//   digitalWrite(cap20, HIGH);
//   digitalWrite(cap10, HIGH);
//   digitalWrite(cap5, LOW);
//   pf_setelah = pzem.pf() + (0.98 - pzem.pf());
//   Serial.println("30uf");
// }

// else if (pf_sebelum >= 0.26 and pf_sebelum <= 0.38) {
//   if (i <= 0) {
//     digitalWrite(cap20, LOW);
//     digitalWrite(cap10, LOW);
//     digitalWrite(cap5, LOW);
//     pf_sebelum = 0;
//     pf_setelah = 0;
//   }
//   else {
//     digitalWrite(cap20, HIGH);
//     digitalWrite(cap10, LOW);
//     digitalWrite(cap5, HIGH);
//     pf_setelah = pzem.pf() + (0.98 - pzem.pf());
//     Serial.println("25uf");

```

```
// }  
  
// }  
  
// else if (pf_sebelum >= 0.39 and pf_sebelum <= 0.51) {  
//   if (i <= 0) {  
//     digitalWrite(cap20, LOW);  
//     digitalWrite(cap10, LOW);  
//     digitalWrite(cap5, LOW);  
//     pf_sebelum = 0;  
//     pf_setelah = 0;  
//   }  
//   else {  
//     digitalWrite(cap20, HIGH);  
//     digitalWrite(cap10, LOW);  
//     digitalWrite(cap5, LOW);  
//     pf_setelah = pzem.pf() + (0.98 - pzem.pf());  
//     Serial.println("20uf");  
//   }  
// }  
  
// else if (pf_sebelum >= 0.52 and pf_sebelum <= 0.64) {  
//   if (i <= 0) {  
//     digitalWrite(cap20, LOW);
```

```

// digitalWrite(cap10, LOW);
// digitalWrite(cap5, LOW);
// pf_sebelum = 0;
// pf_setelah = 0;
// }
// else {
// digitalWrite(cap20, LOW);
// digitalWrite(cap10, HIGH);
// digitalWrite(cap5, HIGH);
// pf_setelah = pzem.pf() + (0.98 - pzem.pf());
//
// Serial.println("15uf" );
// }
// }
// else if (pf_sebelum >= 0.65 and pf_sebelum <= 0.77) {
// if (i <= 0) {
// digitalWrite(cap20, LOW);
// digitalWrite(cap10, LOW);
// digitalWrite(cap5, LOW);
// pf_sebelum = 0;

```

```

//   pf_setelah = 0;
// }
// else {
//   digitalWrite(cap20, LOW);
//   digitalWrite(cap10, HIGH);
//   digitalWrite(cap5, LOW);
//   pf_setelah = pzem.pf() + (0.98 - pzem.pf());
//   Serial.println("10uf");
// }
// }

// else if (pf_sebelum >= 0.78 and pf_sebelum <= 0.90) {
//   if (i <= 0) {
//     digitalWrite(cap20, LOW);
//     digitalWrite(cap10, LOW);
//     digitalWrite(cap5, LOW);
//     pf_sebelum = 0;
//     pf_setelah = 0;
//   }
//   else {
//     digitalWrite(cap20, LOW);
//     digitalWrite(cap10, LOW);

```

```

// digitalWrite(cap5, HIGH);
// pf_setelah = pzem.pf() + (0.98 - pzem.pf());
// Serial.println("5uf");
// }
// }
// else if (pf_sebelum >= 0.91 ) {
//   if (i <= 0) {
//     digitalWrite(cap20, LOW);
//     digitalWrite(cap10, LOW);
//     digitalWrite(cap5, LOW);
//     pf_sebelum = 0;
//     pf_setelah = 0;
//
//   }
//   else {
//     digitalWrite(cap20, LOW);
//     digitalWrite(cap10, LOW);
//     digitalWrite(cap5, LOW);
//     pf_setelah = pzem.pf() + (0.98 - pzem.pf());
//     Serial.println("nan uf");
//   }

```

```

// }

// else {

//   if (pf > 0.01 and pf < 0.98) {

//     pf_sebelum = pf;

//   }

// }

//}

void firebaseSendData() {

  if ((millis() - backTimer) > 7000) {

    Firebase.setFloat(fbdo, F("/tegangan"), v) ? "ok" :
    fbdo.errorReason().c_str();

    Firebase.setFloat(fbdo, F("/arus"), i) ? "ok" :
    fbdo.errorReason().c_str();

    Firebase.setFloat(fbdo, F("/daya"), w) ? "ok" :
    fbdo.errorReason().c_str();

    Firebase.setFloat(fbdo, F("/energi"), e) ? "ok" :
    fbdo.errorReason().c_str();

    Firebase.setFloat(fbdo, F("/frekuensi"), f) ? "ok" :
    fbdo.errorReason().c_str();

    Firebase.setFloat(fbdo, F("/pf_before"), pf_sebelum) ? "ok" :
    fbdo.errorReason().c_str();

    Firebase.setFloat(fbdo, F("/pf_after"), pf_setelah) ? "ok" :
    fbdo.errorReason().c_str();

    backTimer = millis();
  }
}

```



```

    }
}

void firebaseInitial() {
    WiFi.begin(WIFI_SSID, WIFI_PASSWORD);
    Serial.print("Connecting to Wi-Fi");
    while (WiFi.status() != WL_CONNECTED)
    {
        lcd.setCursor(0, 0);
        lcd.print(WIFI_SSID);
        lcd.setCursor(0, 1);
        lcd.print(WIFI_PASSWORD);
        Serial.print(".");
        delay(300);
    }
    Serial.println();
    Serial.print("Connected with IP: ");
    Serial.println(WiFi.localIP());
    Serial.println();
    Serial.printf("Firebase Client v%s\n\n",
    FIREBASE_CLIENT_VERSION);
    config.api_key = API_KEY;

```

```
auth.user.email = USER_EMAIL;

auth.user.password = USER_PASSWORD;

config.database_url = DATABASE_URL;

config.token_status_callback    =    tokenStatusCallback;    //see
addons/TokenHelper.h

Firebase.begin(&config, &auth);

Firebase.reconnectWiFi(true);

Firebase.setDoubleDigits(5);

}
```

LAMPIRAN B

Gambar Dokumentasi



Perancangan Perangkat Keras



Pengukuran dengan alat ukur cosphi analog



Tampak Keseluruhan Alat



Tampak Samping Pada Alat



Tampak Depan Pada Alat



Tampak Dalam Pada Alat