

LAMPIRAN A

Listing Program Arduino Pada *Node Transmitter*

```
#include <LiquidCrystal_I2C.h>
#include <Wire.h>
#include <Keypad.h>
#include <DHT.h>
DHT dht(A14, DHT11);
LiquidCrystal_I2C lcd(0x27, 20, 4);
#include <DS3231.h>
#include "RTClib.h"
int jam, menit, detik;
RTC_DS3231 rtc;
String myTime;
unsigned long MillisAwal = 0;
unsigned long Mi = 0;
char key;
long duration;
float distance, jarak;
float tinggi;
volatile byte rpmcount;
volatile unsigned long last_micros;
unsigned long timeold;
unsigned long timemeasure = 2.00;
int timetoSleep = 1;
unsigned long sleepTime = 15;
unsigned long timeNow;
int countThing = 0;
int GPIO_pulse = 2;
float rpm, rps;
float radius = 0.125;
anemometer wing
float velocity_kmh;
float angin;
float omega = 0;
float calibration_value = 1.1;
int kelembaban ;
int suhu ;
```

```

const int pin_interrupt = 3;
long int jumlah_tip = 0;
float curah_hujan = 0.00;
float curah_hujan_per_menit = 0.00;
float curah_hujan_per_jam = 0.00;
float curah_hujan_per_hari = 0.00;
float curah_hujan_hari_ini = 0.00;
float temp_curah_hujan_per_menit = 0.00;
float temp_curah_hujan_per_jam = 0.00;
float temp_curah_hujan_per_hari = 0.00;
float milimeter_per_tip = 1.7;
String cuaca;
volatile boolean flag = false;
#define trig 49
#define echo 51
unsigned long waktusSesudah;
unsigned long waktusebelum = 0;
const byte ROWS = 4;
const byte COLS = 4;
char keys[ROWS][COLS] = {
    {'1', '2', '3', 'A'},
    {'4', '5', '6', 'B'},
    {'7', '8', '9', 'C'},
    {'*', '0', '#', 'D'}
};
byte rowPins[ROWS] = {A0, A1, A2, A3};
byte colPins[COLS] = {A4, A5, A6, A7};
Keypad keypad = Keypad(makeKeymap(keys), rowPins, colPins,
ROWS, COLS);
int value = 122;
int count = 0;

void setup() {
  Serial.begin(9600);
  Serial1.begin(115200);
  pinMode(trig, OUTPUT);
  pinMode(echo, INPUT);
  if (! rtc.begin()) {

```

```

Serial.println("tidak menemukan RTC");
while (1);
}
if (rtc.lostPower()) {
    Serial.println("daya RTC hilang, set waktu");
    rtc.adjust(DateTime(F(__DATE__)), F(__TIME__)));
}
lcd.begin();
lcd.backlight();
lcd.setCursor(0, 0);
lcd.print(" Sistem EWS ");
lcd.setCursor(0, 1);
lcd.print(" LoRa Transmiter ");
delay(2000);
lcd.clear();
setkecepatan_angin();
set_rain();
dht.begin();
}

void loop() {
    DateTime now = rtc.now();
    detik = now.second();
    jam = now.hour();
    menit = now.minute();
    kecepatan_angin();
    sen_rain();
    ultrasonik();
    Serial.println(distance);
    dht_11();
    TAMPILLCD();
    String kirimData = "(" + String(tinggi) + "," + String(angin) + "," +
    String(curah_hujan) + "," + String(curah_hujan_per_menit) + "," +
    String(suhu) + "," + String(kelembaban) + ")";
    Serial1.println(kirimData);
    Serial.println(kirimData);
}

```

```

void setkecepatan_angin() {
    pinMode(GPIO_pulse, INPUT);
    digitalWrite(GPIO_pulse, LOW);
    detachInterrupt(digitalPinToInterrupt(GPIO_pulse));
    delay(10);
    attachInterrupt(digitalPinToInterrupt(GPIO_pulse), rpm_anemometer,
RISING);
    rpmcount = 0;
    rpm = 0;
    timeold = 0;
    timeNow = 0;
}
void kecepatan_angin()
{
    if ((millis() - timeold) >= timemeasure * 1000)
    {
        countThing++;
        detachInterrupt(digitalPinToInterrupt(GPIO_pulse));
        rps = float(rpmcount) / float(timemeasure);
        rpm = 60 * rps;
        omega = 2 * PI * rps;
        angin = omega * radius * calibration_value;
        velocity_kmh = angin * 3.6;
        if (countThing == 1)
        {
            countThing = 0;
        }
        timeold = millis();
        rpmcount = 0;
        attachInterrupt(digitalPinToInterrupt(GPIO_pulse), rpm_anemometer,
RISING);
    }
}
void rpm_anemometer()
{
    if (long(micros() - last_micros) >= 5000)
    {
        rpmcount++;
        last_micros = micros();
    }
}

```

```

void ultrasonik ()
{
    digitalWrite(trig, LOW);
    delayMicroseconds(2);
    digitalWrite(trig, HIGH);
    delayMicroseconds(10);
    digitalWrite(trig, LOW);
    duration = pulseIn(echo, HIGH);
    distance = (float)duration * 0.0343 / 2.00;
    tinggi = distance;
    delay(10);
}

void hitung_curah_hujan()
{
    flag = true;
    if (flag == true)
    {
        curah_hujan_per_menit += milimeter_per_tip;
        jumlah_tip++;
        flag = false;
    }
}
void set_rain()
{
    Serial.begin(9600);
    pinMode (pin_interrupt, INPUT_PULLUP);
    attachInterrupt (digitalPinToInterrupt(pin_interrupt),
hitung_curah_hujan, FALLING);
}
void sen_rain()
{
    if (millis() - waktusebelum > 60000) {
        curah_hujan += curah_hujan_per_menit;
        curah_hujan_per_menit = 0.00;
        jumlah_tip = 0;
        waktusebelum = millis();
    }
}

```

```
if (jam == 23 && menit == 59 && detik > 58) {
    curah_hujan = 0.00;
    Serial.println("reset");
}

void dht_11() {
    kelembaban = dht.readHumidity();
    suhu = dht.readTemperature();
}

void TAMPILLCD() {

    key = keypad.getKey();
    if (key == 'A') {
        count = 0;
        lcd.clear();
    }

    else if (key == 'B') {
        count = 1;
        lcd.clear();
    }

    else if (key == 'C') {
        count = 2;
        lcd.clear();
    }

    else if (key == 'D') {
        count = 3;
        lcd.clear();
    }

    else if (key == '#') {
        count = 4;
        lcd.clear();
    }
}
```

```

if (count == 0) {
    lcd.setCursor(0, 0);
    lcd.print(" Monitoring Air ");
    lcd.setCursor(0, 2);
    lcd.print("Tinggi = ");
    lcd.print(tinggi);
    lcd.print(" Cm");
}
if (count == 1) {
    lcd.setCursor(0, 0);
    lcd.print(" Monitoring Suhu ");
    lcd.setCursor(0, 2);
    lcd.print("Kelembaban= ");
    lcd.print("77");
    lcd.print("%");
    lcd.setCursor(0, 3);
    lcd.print("Suhu     = ");
    lcd.print("29");
    lcd.print(" *C");
}
if (count == 2) {
    myTime = myTime +jam + "." + menit + "." + detik;
    lcd.setCursor(0, 0);
    lcd.print(" Monitoring Hujan ");
    lcd.setCursor(0, 1);
    lcd.print("Jam : " + myTime);
    myTime = "";
    lcd.print(" WIB");
    lcd.setCursor(0, 2);
    lcd.print("PerHri: ");
    lcd.print(curah_hujan);
    lcd.print(" ml/cm2");
    lcd.setCursor(0, 3);
    lcd.print("PerMnt: ");
    lcd.print(curah_hujan_per_menit);
    lcd.print(" ml/cm2");
}

```

```
if (count == 3) {
    lcd.setCursor(0, 0);
    lcd.print(" Monitoring Angin ");
    lcd.setCursor(0, 2);
    lcd.print("Kec.Angin= ");
    lcd.print(angin);
    lcd.print("m/s");
}
if (count == 4) {
    if (key != NO_KEY) {
        switch (key) {
            case '1':
                value = (value * 10) + 1;
                break;
            case '2':
                value = (value * 10) + 2;
                break;
            case '3':
                value = (value * 10) + 3;
                break;
            case '4':
                value = (value * 10) + 4;
                break;
            case '5':
                value = (value * 10) + 5;
                break;
            case '6':
                value = (value * 10) + 6;
                break;
            case '7':
                value = (value * 10) + 7;
                break;
            case '8':
                value = (value * 10) + 8;
                break;
            case '9':
                value = (value * 10) + 9;
                break;
            case '0':
```

```
    value = (value * 10);
    break;
case '*':
    value = 0;
    break;
}
}
lcd.setCursor(0, 0);
lcd.print("Kalibrasi : ");
lcd.print(value);
lcd.print(" cm");
}
}
```

LAMPIRAN B

Listing Program LoRa Pada Node Transmitter

```
#include "heltec.h"
#include "images.h"
#define BAND 915E6
String FullData;
unsigned int counter = 0;
String rssi = "RSSI --";
String packSize = "--";
String packet ;
unsigned long terima;
unsigned long MillisAwal = 0;

void logo()
{
    Heltec.display->clear();
    Heltec.display->drawXbm(0, 5, logo_width, logo_height, logo_bits);
    Heltec.display->display();
}

void setup()
{
    Heltec.begin(true /*DisplayEnable Enable*/, true
/*Heltec.Heltec.Heltec.LoRa Disable*/, true /*Serial Enable*/, true
/*PABOOST Enable*/, BAND /*long BAND*/);
    Heltec.display->init();
    Heltec.display->flipScreenVertically();
    Heltec.display->setFont(ArialMT_Plain_10);
    logo();
    delay(1500);
    Heltec.display->clear();

    Heltec.display->drawString(0, 0, "Heltec.LoRa Initial success!");
    Heltec.display->display();
    delay(1000);
}
```

```
void loop() {
    if (Serial.available()) {
        FullData = Serial.readStringUntil('\n');
        Serial.println(FullData);
    }
    Heltec.display->clear();
    Heltec.display->set.TextAlignment(TEXT_ALIGN_LEFT);
    Heltec.display->setFont(ArialMT_Plain_10);
    Heltec.display->drawString(0, 0, "KIRIM PAKET : ");
    Heltec.display->drawString(90, 0, String(counter));
    Heltec.display->display();
    unsigned long MillisSekarang = millis();
    if (MillisSekarang - MillisAwal >= 1000) {
        MillisAwal = MillisSekarang;
        LoRa.beginPacket();
        LoRa.setTxPower(20, RF_PA_CONFIG_PASELECT_PABOOST);
        LoRa.print(FullData);
        LoRa.endPacket();
        counter++;
    }
}
```

LAMPIRAN C

Listing Program LoRa Pada Node Receiver

```
#include "heltec.h"
#include "images.h"
#include <LiquidCrystal_I2C.h>
#include <Wire.h>
LiquidCrystal_I2C lcd(0x27, 20, 4);
#define tombol 37
int itung = 1;
#define alarm 22

#define BAND  915E6
String rssi = "RSSI --";
String packSize = "--";
String packet;
unsigned long MillisAwal = 0;
unsigned long Millisreset = 0;
float tinggi, angin, hujan1, hujan2, suhu, kelembaban;
String tinggistring, anginstring, hujan1string, hujan2string, suhustring,
kelembabanstring;

void setup() {
    Heltec.begin(true /*DisplayEnable Enable*/, true
/*Heltec.Heltec.Heltec.LoRa Disable*/, true /*Serial Enable*/, true
/*PABOOST Enable*/, BAND /*long BAND*/);
    Heltec.display->init();
    Heltec.display->flipScreenVertically();
    Heltec.display->setFont(ArialMT_Plain_10);
    logo();
    delay(1500);
    Heltec.display->clear();
    Heltec.display->drawString(0, 0, "Heltec.LoRa Initial success!");
    Heltec.display->drawString(0, 10, "Wait for incoming data...\"");
    Heltec.display->display();
    LoRa.receive();
    lcd.backlight();
    lcd.begin();
    pinMode(alarm, OUTPUT);
```

```

pinMode(tombol, INPUT_PULLUP);
digitalWrite(alarm, LOW);
lcd.setCursor(0, 0);
lcd.print("    Sistem EWS    ");
lcd.setCursor(0, 1);
lcd.print(" LoRa Receiver ");
lcd.clear();
}

void loop() {
int packetSize = LoRa.parsePacket();
if (packetSize) {
cbk(packetSize);
Serial.println(packet);
parsing(packet);
antares.add("Tinggi Air", tinggi);
antares.add("Curah hujan", hujan1);
antares.add("Kecepatan angin", angin);
antares.add("Suhu", suhu);
antares.add("Kelembaban", kelembaban);
lcdprint();
}
}

void lcdprint() {
if (digitalRead(tombol) == LOW ) {
lcd.clear();
itung++;
delay(200);
}
if (itung == 1) {
lcd.setCursor(0, 0);
lcd.print(" Monitoring Air  ");
lcd.setCursor(0, 2);
lcd.print("Tinggi = ");
lcd.print(tinggi);
lcd.print(" Cm");
}
}

```

```
if (itung == 2) {  
    lcd.setCursor(0, 0);  
    lcd.print(" Monitoring Suhu ");  
    lcd.setCursor(0, 2);  
    lcd.print("Kelembaban= ");  
    lcd.print("77");  
    lcd.print("%");  
    lcd.setCursor(0, 3);  
    lcd.print("Suhu = ");  
    lcd.print("29");  
    lcd.print(" *C");  
}  
  
if (itung == 3) {  
    lcd.setCursor(0, 0);  
    lcd.print(" Monitoring Hujan ");  
    lcd.setCursor(0, 2);  
    lcd.print("PerHri: ");  
    lcd.print(hujan1);  
    lcd.print(" ml/cm2");  
    lcd.setCursor(0, 3);  
    lcd.print("PerMnt: ");  
    lcd.print(hujan2);  
    lcd.print(" ml/cm2");  
}  
  
if (itung == 4) {  
    lcd.setCursor(0, 0);  
    lcd.print(" Monitoring Angin ");  
    lcd.setCursor(0, 2);  
    lcd.print("Kec.Angin= ");  
    lcd.print(angin);  
    lcd.print("m/s");  
}  
if (itung == 5) {  
    itung = 1;  
}  
delay(5);  
}
```

```
void parsing(String data) {  
    byte awal = data.indexOf('(');  
    byte koma1 = data.indexOf(',');  
    byte koma2 = data.indexOf(',', koma1 + 1);  
    byte koma3 = data.indexOf(',', koma2 + 1);  
    byte koma4 = data.indexOf(',', koma3 + 1);  
    byte koma5 = data.indexOf(',', koma4 + 1);  
    byte akhir = data.indexOf(')');  
  
    tinggistring = data.substring(awal + 1, koma1);  
    anginstring = data.substring(koma1 + 1, koma2);  
    hujan1string = data.substring(koma2 + 1, koma3);  
    hujan2string = data.substring(koma3 + 1, koma4);  
    suhustring = data.substring(koma4 + 1, koma5);  
    kelembabanstring = data.substring(koma5 + 1, akhir);  
  
    tinggi = tinggistring.toFloat();  
    angin = anginstring.toFloat();  
    hujan1 = hujan1string.toFloat();  
    hujan2 = hujan2string.toFloat();  
    suhu = suhustring.toFloat();  
    kelembaban = kelembabanstring.toFloat();  
    if (tinggi > 100) {  
        digitalWrite(alarm, HIGH);  
    }  
    else {  
        digitalWrite(alarm, LOW);  
    }  
}
```

LAMPIRAN D

Listing Program Arduino Pada Node Receiver

```
#include <String.h>
#include <LiquidCrystal_I2C.h>
#include <Wire.h>
LiquidCrystal_I2C lcd(0x27, 20, 4);
unsigned long MillisAwal = 0;
unsigned long milislcd;
unsigned long Mi = 0;
int berhasil = 0;
int jmlkirim = 0;
float tinggi, angin, hujan1, hujan2, suhu, kelembaban;
String tinggistring, anginstring, hujan1string, hujan2string, suhustring,
kelembabanstring;
unsigned long terima, kirim, cd;
String FullData;
String Write_API_key = "MQOPIYXIH4A5C8QV";
String apn = "TSEL-SNS";

void setup() {
    Serial.begin(115200);
    Serial1.begin(9600);
    Serial3.begin(115200);
    SetupModule();
}

void loop() {
    if (Serial3.available()) {
        String FullData;
        FullData = Serial3.readStringUntil('\n');
        parsing(FullData);
    }
    unsigned long MillisSekarang = millis();
    if (MillisSekarang - MillisAwal >= 50) {
        MillisAwal = MillisSekarang;
        kirimdata();
    }
}
```

```
int data1, data2, data3, data4, data5;

void kirimdata() {
Serial1.println("AT+CIPSTART=\"TCP\",\"api.thingspeak.com\",\"80\"");
delay(1000);
ShowSerialData();
Serial1.println("AT+CIPSEND");
delay(1000);
ShowSerialData();
String str = "GET https://api.thingspeak.com/update?api_key=" +
Write_API_key + "&field1=" + String(suhu) + "&field2=" +
String(kelembaban) + "&field3=" + String(tinggi) + "&field4=" +
String(angin) + "&field5=" + String(hujan1);
Serial1.println(str);
delay(2000);
Serial1.println((char)26);
delay(2000);
Serial1.println("AT+CIPSHUT");
delay(500);
ShowSerialData();
delay(1000);
ShowSerialData();
delay(1000);
str = "";
delay(1000);
}

void SetupModule() {
if (Serial1.available()) Serial.write(Serial1.read());
Serial1.println("AT"); delay(2000);
ShowSerialData();
Serial1.println("AT+CPIN?"); delay(2000);
ShowSerialData();
Serial1.println("AT+CREG?"); delay(2000);
ShowSerialData();
Serial1.println("AT+CGATT?"); delay(2000);
ShowSerialData();
Serial1.println("AT+CIPSHUT"); delay(2000);
}
```

```

ShowSerialData();
Serial1.println("AT+CIPSTATUS"); delay(2000);
ShowSerialData();
Serial1.println("AT+CIPMUX=0"); delay(2000);
ShowSerialData();
Serial1.println("AT+CSTT=\\" + apn + "\\\"); delay(2000);
ShowSerialData();
Serial1.println("AT+CIICR"); delay(2000);
ShowSerialData();
Serial1.println("AT+CIFSR"); delay(2000);
ShowSerialData();
Serial1.println("AT+CIPSPRT=0"); delay(2000);
ShowSerialData();
}

void ShowSerialData() {
    while (Serial1.available() != 0)
        Serial.write(Serial1.read());
    delay(1000);
}

void TerimaLORA() {
    if (Serial3.available()) {
        String FullData;
        FullData = Serial3.readStringUntil('\n');
        parsing(FullData);
        Serial.println(FullData);
    }
}

void parsing(String data) {
    byte awal = data.indexOf('(');
    byte koma1 = data.indexOf(',');
    byte koma2 = data.indexOf(',', koma1 + 1);
    byte koma3 = data.indexOf(',', koma2 + 1);
    byte koma4 = data.indexOf(',', koma3 + 1);
    byte koma5 = data.indexOf(',', koma4 + 1);
    byte akhir = data.indexOf(')');
}

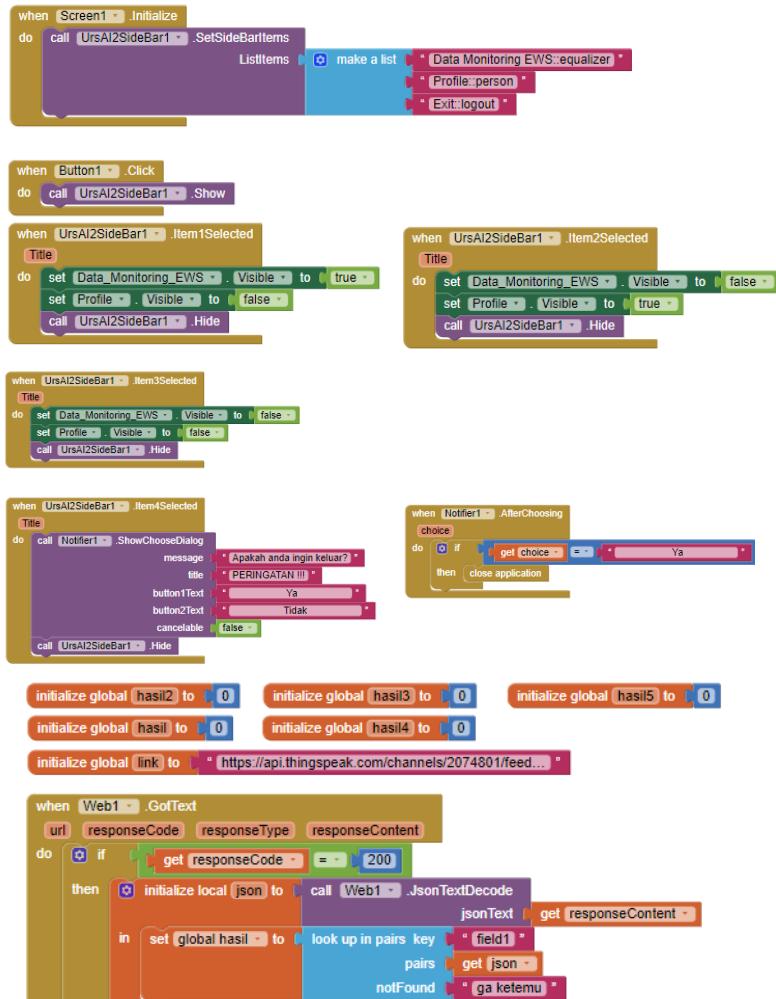
```

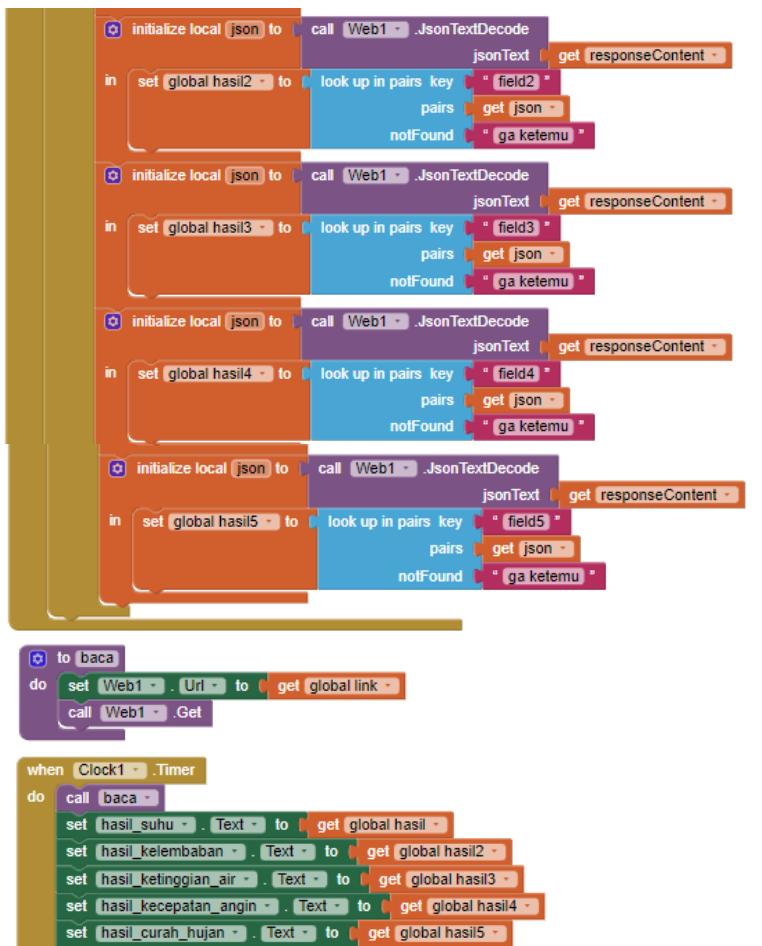
```
tinggistring = data.substring(awal + 1, koma1);
anginstring = data.substring(koma1 + 1, koma2);
hujan1string = data.substring(koma2 + 1, koma3);
hujan2string = data.substring(koma3 + 1, koma4);
suhustring = data.substring(koma4 + 1, koma5);
kelembabanstring = data.substring(koma5 + 1, akhir);

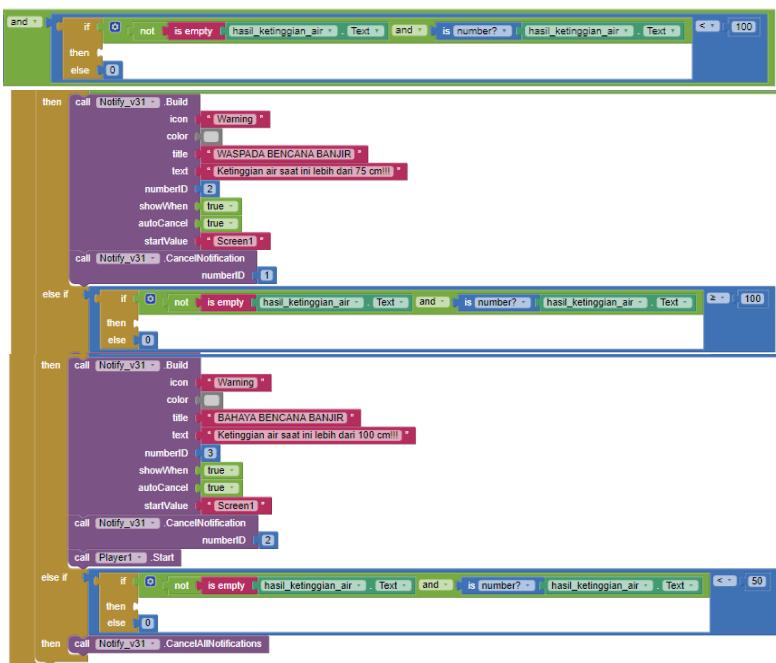
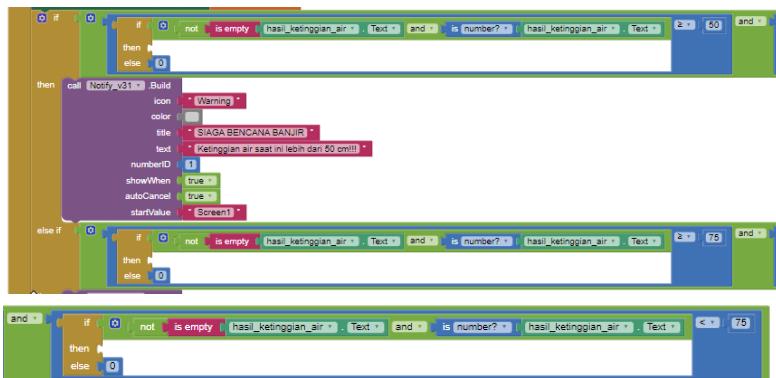
tinggi = tinggistring.toFloat();
angin = anginstring.toFloat();
hujan1 = hujan1string.toFloat();
hujan2 = hujan2string.toFloat();
suhu = suhustring.toFloat();
kelembaban = kelembabanstring.toFloat();
}
```

LAMPIRAN E

Listing Program Pada MIT App Inventor







LAMPIRAN F
Hasil Alat

A. Gambar Tampak Depan *Node Trasmitter*



B. Gambar Tampak Depan *Node Trasmitter*



C. Gambar Tampak Samping



D. Gambar Keseluruhan EWS



E. Gambar *Panel Box Transmitter*



F. Gambar Panel Box Receiver



G. Data Iradiasi Matahari Dari PVsyst

Geographical site parameters, new site						
	Geographical Coordinates	Monthly meteo	Interactive Map			
Site	Politeknik Negeri Cilacap (Indonesia)					
Data source	Meteonorm 8.0 (1991-2009), Sat=100%					
	Global horizontal irradiation kWh/m ² /mth	Horizontal diffuse irradiation kWh/m ² /mth	Temperature °C	Wind Velocity m/s	Linke turbidity [·]	Relative humidity %
January	129,4	68,6	26,2	3,80	4,624	80,0
February	155,8	67,6	26,6	3,19	4,040	79,7
March	181,4	78,1	27,6	2,30	3,899	79,3
April	182,9	71,8	28,5	1,41	3,537	80,4
May	174,8	79,6	29,2	1,79	3,379	79,9
June	148,0	79,0	28,2	1,80	3,576	82,7
July	149,9	80,5	28,3	2,39	3,719	81,4
August	158,4	82,0	28,3	2,61	3,870	81,1
September	160,8	81,0	27,7	2,10	3,662	83,6
October	150,9	80,5	27,9	1,61	3,792	82,9
November	108,9	69,0	27,3	2,40	4,109	84,1
December	105,6	73,3	26,9	3,59	5,147	80,5
Year	1807,0	910,9	27,7	2,4	3,946	81,3