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LAMPIRAN A

DAFTAR PROGRAM ARDUINO

```
const double target = 200;

const double mixer = 50;

const float kP = 2.3;

const float kI = 15;

const float kD = 8;

//dimmer

#include <RBDdimmer.h>

dimmerLamp dim(7);

//lcd

#include <LiquidCrystal_I2C.h>

LiquidCrystal_I2C lcd(0x27, 20, 4);

//sensor

#include "MAX6675.h"

MAX6675 thermoCouple;
```

```
//pid

#include <PID_v1.h>

double pidInput, pidOutput;

PID myPID(&pidInput, &pidOutput, &target, kP, kI, kD, DIRECT);

void setup() {

  Serial.begin(9600);

  //dimmer

  dim.begin(TOGGLE_MODE, OFF);

  dim.toggleSettings(0, 100);

  //lcd

  lcd.begin();

  lcd.backlight();

  lcd.clear();

  //sensor

  thermoCouple.begin(47, 49, 51);

  //tombol

  pinMode(53, INPUT_PULLUP);

  //pid

  myPID.SetOutputLimits(0, 100);
```

```
myPID.SetMode(AUTOMATIC);

//motor

pinMode(4, OUTPUT);

pinMode(5, OUTPUT);

}

bool statusPower = false;

bool statusMotor = false;

float lastPowerValue = 0;

float powerValue = 0;

void loop() {

    double sensorVal = 0;

    for (int i = 0; i < 10; i++) {

        thermoCouple.read();

        sensorVal += thermoCouple.getTemperature();

        delay(100);

    }

    sensorVal = sensorVal / 10;

    if (statusPower) {
```

```
pidInput = sensorVal;

myPID.Compute();

powerValue = pidOutput;

if (sensorVal > mixer) {
    statusMotor = true;
}

else if (sensorVal < mixer - 10) {
    statusMotor = false;
}

}

else {

    powerValue = 0;

    statusMotor = false;

}

if (statusMotor) {

    analogWrite(4, 150);

    analogWrite(5, 0);

}

else {

    digitalWrite(4, 0);
```



```
digitalWrite(5, 0);  
  
}  
  
if (powerValue != lastPowerValue) {  
    lastPowerValue = powerValue;  
    dim.setPower(powerValue);  
}  
  
if (digitalRead(53) == LOW) {  
    statusPower = !statusPower;  
    if (statusPower) {  
        dim.setState(ON);  
    }  
    else {  
        dim.setState(OFF);  
    }  
    while (digitalRead(53) == LOW) {  
        delay(100);  
    }  
}  
  
lcd.setCursor(0, 0);  
lcd.print("      ");
```

```
lcd.setCursor(0, 0);

lcd.print("Status:");

if (statusPower) {

    lcd.print("Aktif");

}

else {

    lcd.print("Nonaktif");

}

lcd.setCursor(0, 1);

lcd.print("Suhu Target:");

lcd.print(target);

lcd.setCursor(0, 2);

lcd.print("          ");

lcd.setCursor(0, 2);

lcd.print("Suhu Aktual:");

lcd.print(sensorVal);

lcd.setCursor(0, 3);

lcd.print("          ");

lcd.setCursor(0, 3);

lcd.print("Power:");
```

```
lcd.print(powerValue);  
  
Serial.print(target);  
  
Serial.print('\t');  
  
Serial.print(sensorVal);  
  
Serial.print('\t');  
  
Serial.print(powerValue);  
  
Serial.print('\n');  
  
}
```


LAMPIRAN B

Alat Sangrai dan Hasil *Roasting* Biji Kopi



Alat Sangrai Biji Kopi



Hasil Biji Kopi *Light Roast*



Hasil Biji Kopi *Medium Roast*



Hasil Biji Kopi *Dark Roast*

BIODATA PENULIS



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Motto : Try to learn to settle it yourself

Riwayat Pendidikan

TK Kencana	Tahun 2006-2007
SD Negeri Gunung Simping 01 Cilacap	Tahun 2007-2013
SMP Negeri 08 Cilacap	Tahun 2013-2016
SMK Migas Muhammadiyah Cilacap	Tahun 2016-2019
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