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LAMPIRAN B

Berikut kode pemrograman

```
#include <Wire.h>

#define windPin 2 // Receive the data from sensor

//Program Kecepatan Angin

// Constants definitions

const float pi = 3.14159265; // pi number

int period = 1000; // Measurement period (miliseconds)

int delaytime = 1000; // Time between samples (miliseconds)

int radio =90; // Distance from center windmill to outer cup (mm)

int jml_celah = 18; //jumlah celah sensor
```

// Variable definitions

```
unsigned int Sample = 0; // Sample number

unsigned int counter= 0; // B/W counter for sensor

unsigned int RPM = 0; // Revolutions per minute

float speedwind = 0; // Wind speed (m/s)
```

A-3

```
//Program Tegangan

int analogPin= A0; //pin arduino yang terhubung

float Vmodul = 0.0;

float R1 = 30000.0; // Resistor 30k

float R2 = 7500.0; // Resistor 7500 ohm

int value =0;

float HasilTegangan = 0.0;
```

B-1

```
//Program Arus
double vRef = 5000;
int iter = 2000;
double vMid = (vRef/2 );
double mVpA = 0.066;
double pADC = 0;
unsigned long awalPrint = 0;
unsigned long jeda = 3000;
const int currentPin = A3;
double HasilArus;
//program Daya
float HasilDaya = 0.0;
#include <LCD_I2C.h>
LCD_I2C lcd(0x27, 20, 4); // Default address of most PCF8574
modules, change according
// waktu awal
unsigned long wakn=0; // waktu awal kirim nodemcu
unsigned long wats=0; // waktu awal tampil serial

void setup() {
lcd.begin();           // this stop the library(LCD_I2C) from calling
Wire.begin()
lcd.backlight();
Serial.begin(9600);
//Kecepatan Angin
```

```

pinMode(2, INPUT);
digitalWrite(2, HIGH);
pinMode(analogPin, INPUT);}

void loop() {
unsigned long wsts=millis(); // waktu sekarang tampil serial
if(wsts-wats > 2000) // serial tampil setiap 1 second{

//Program Tegangan
value = analogRead (analogPin);
Vmodul= (value*5.0)/1024.0;
HasilTegangan = Vmodul/ (R2/(R1+R2));
//lcd.print ("Tegangan=");
//lcd.print (Vmodul,2);
//lcd.print(" Volt");
Serial.print("Tegangan=");
Serial.println (HasilTegangan,1);
lcd.setCursor(0, 0);
lcd.print ("Tegangan=");
lcd.print(HasilTegangan,1);
lcd.print (" V");

//Program Arus
double adc = 0;
double analog0 = analogRead(currentPin);
for (int i=0; i<iter; i++){
adc += analogRead(currentPin); }

```

```
double avg_adc = adc/iter;
double vAvg = (avg_adc/1023.0)*vRef;
double vDelta = vMid - vAvg;
HasilArus = vDelta/mVpA;
HasilArus = abs(HasilArus/1000);
if (HasilArus<=0){
    HasilArus== 0; }
if (millis()-awalPrint>jeda){
    awalPrint = millis();
    pADC = adc; }
Serial.print("Arus= ");
Serial.print (HasilArus,2);
Serial.println (" A");
lcd.setCursor(0, 1);
lcd.print ("Arus = ");
lcd.print (HasilArus,2);
lcd.print ( " A");

//Program Daya
HasilDaya = HasilTegangan*HasilArus;
//program daya
Serial.print("Daya= ");
Serial.print (HasilDaya,3);
Serial.println (" Watt");
lcd.setCursor(0, 2);
lcd.print ("Daya = ");
```

```
lcd.print (HasilDaya,3);
lcd.print ( " W");
Sample++;
//Serial.print(Sample);
//Serial.print(": Start measurement...");
windvelocity();
//Serial.println(" finished.");
//Serial.print("Counter: ");
//Serial.print(counter);
//Serial.print("; RPM: ");
RPMcalc();
//Serial.print(RPM);
WindSpeed();
Serial.print("Wind speed:");
Serial.print(speedwind);
Serial.print(" [m/s]");
Serial.println();
lcd.setCursor(0,3);
lcd.print("Angin = ");
lcd.setCursor(10, 3);
lcd.print(speedwind);
lcd.print ("[m/s]");
wats=millis();
data_kirim();}

// Measure wind speed
void windvelocity(){
```

```

speedwind = 0;
counter = 0;
attachInterrupt(0, addcount, CHANGE);
unsigned long millis();
long startTime = millis();
while(millis() < startTime + period) {}

detachInterrupt(1);}

void RPMcalc(){
RPM=((counter/jml_celah)*60)/(period/1000); // Calculate revolutions
per minute (RPM)}

void WindSpeed(){
speedwind = ((2 * pi * radio * RPM)/60) / 1000; // Calculate wind speed
on m/s}

void addcount(){
counter++;}

void data_kirim() {
//menampung data yang akan di kirimkan ke nodemcu
Serial.println();
String dkirim = "#" + String(HasilTegangan) + "#" +
String(HasilArus,2) + "#" + String(HasilDaya,3) + "#" + String
(speedwind) + "#" + "$" ;
Serial.println(dkirim);
Serial.println();
}

```

Program NodeMCU ESP8266

```
#include <ESP8266HTTPClient.h>
#include <ESP8266WiFi.h>
#include <WiFiClient.h>

float angin ;
float tegangan ;
float arus ;
float daya ;

//parsing data arduino mega
bool parsing = false;

String sData,ardata[5]; // sData= data serial, data= jumlah data yang di
parsing
//variable wifi
const char* id = "BOLTSuper4G-1234";
const char* pw = "taufik456";
//inisialisasi variable host adress server
//const char* server = "tugasakhirdanu.000webhostapp.com";(semisal
mau dikirim ke server gratis)
const char* server = "monitoringturbaningin.sazking.my.id";
//waktu awal
unsigned long wakw=0;//waktu awal kirim web
void setup() {
Serial.begin (9600);//pada saat kirim data ke nodemcu maka nilai Rx
nodeMCU dicabut
//inisialisasi host
WiFi.hostname("NodeMCU");
```

```
//konek wifi
WiFi.begin(id, pw);
//cek koneksi
while(WiFi.status() != WL_CONNECTED){
    //coba koneksi terus
    Serial.print(".");
    delay(500);
}
//apabila terkoneksi
Serial.println("Berhasil Koneksi Dengan Wifi");
void loop() {
    //baca data dari NodeMCU
    //Sediakan variabel untuk menampung data
    //Selama data serial ada/tersedia
    while (Serial.available()) {
        //Ambil data serial kemudian masukan ke variable data
        char inChar = Serial.read();
        sData += inChar;
        if(inChar == '$'){
            parsing = true;
        }
        if(parsing){
            int q = 0;
            for(int i = 0; i < sData.length(); i++){
                if(sData[i] == '#'){
                    q++;
                    ardata[q] = "";
                } else {
                    ardata[q] += sData[i];
                }
            }
        }
    }
}
```

```
Serial.println(ardata[1]);
Serial.println(ardata[2]);
Serial.println(ardata[3]);
Serial.println(ardata[4]);
Serial.println();
parsing = false;
sData = "";
angin = ardata[4].toFloat() ;
tegangan = ardata[1].toFloat() ;
arus = ardata[2].toFloat() ;
daya = ardata[3].toFloat() ; }
//kirim data ke database
WiFiClient client;
const int httpPort = 80;
//mencari data koneksi
if(!client.connect(server, httpPort)){
  Serial.println("gagal koneksi ke web");
  return ;
}
unsigned long wskw = millis();
if((wskw-wakw)>5000){
  //apabila terkoneksi ke web maka kirim data
  HTTPClient http;
  //siapkan link kirim data
  //kirim ke webserver
```

```
String Link = "http://" + String(server) + "/bacasensor.php?angin=" +
String(angin,1) + "&tegangan=" + String(tegangan,1) + "&arus=" +
String(arus,1) + "&daya=" + String(daya,1) ;
//kirim ke website gratis
//String Link = "http://" + String(server) +
"db_multisensor/bacاسensor.php?angin=" + String(angin,1) +
"&tegangan=" + String(tegangan,1) + "&arus=" + String(arus,1) +
"&daya=" + String(daya,1) ;
//eksekusi link
http.begin(client,Link);
http.GET();
//tangkap respong kirim data
String respon = http.getString();
Serial.println(respon);
wakw=millis();
}
```

BIODATA PENULIS



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Hobi	:	Membaca
Motto	:	Proses yang sungguh sungguh, akan melahirkan cerita yang jujur

Riwayat Pendidikan

- | | |
|---|-----------------|
| • SD Negeri 01 Argopeni | Tahun 2006-2013 |
| • SMP Negeri 7 Kebumen | Tahun 2013-2016 |
| • SMK Negeri 2 Kebumen | Tahun 2016-2019 |
| Jurusan Teknik Instalasi Tenaga Listrik | |
| • Politeknik Negeri Cilacap | Tahun 2019-2022 |
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Penulis telah mengikuti seminar proposal pada tanggal 17 Juni 2022 sebagai salah satu persyaratan untuk memperoleh gelar Ahli Madya (A.Md)