

LAMPIRAN A

Daftar Program Arduino Ide

A. Program RTC

```
#include "RTClib.h"
RTC_DS3231 rtc;
int tanggal, bulan, tahun, jam, menit, detik, jam1, jam2,
menit1, menit2;
char dataHari[7][12] = {"Minggu", "Senin", "Selasa",
"Rabu", "Kamis", "Jum'at,", "Sabtu"};
String hari;
void setup() {
    Serial.begin(115200);
#ifndef ESP8266
    while (!Serial);
#endif
    if (! rtc.begin()) {
        Serial.println("RTC Tidak Ditemukan");
        Serial.flush();
        abort();
    }
    //Atur Waktu
    //rtc.adjust(DateTime(F(__DATE__), F(__TIME__)));
    // rtc.adjust(DateTime(2022, 5, 26, 23, 26, 0));
}
void loop() {
    DateTime now = rtc.now();
    hari = dataHari [now.dayOfTheWeek()];
    tanggal = now.day(), DEC;
    bulan = now.month(), DEC;
    tahun = now.year(), DEC;
    jam = now.hour(), DEC;
    menit = now.minute(), DEC;
    detik = now.second(), DEC;
```

```
    Serial.println(String() + hari + "," + tanggal + "-" + bulan +  
    "-" + tahun);  
    Serial.println(String() + jam + ":" + menit + ":" + detik);  
    Serial.println();  
    delay(500);  
}
```

B. Program Sensor Turbidity

```
static float kekeruhan;  
static float teg;  
void setup() {  
    Serial.begin(115200);  
}  
void loop() {  
    int val = analogRead(0);  
    teg = val*(5/1024);  
    kekeruhan = 100.00-(teg/5)*100.00;  
    Serial.print (teg);  
    Serial.print(" ");  
    Serial.print(" Nilai ADC = ");  
    Serial.print(val);  
    Serial.print(" Nilai Kekeruhan = ");  
    Serial.print(kekeruhan);  
    Serial.println (" NTU");  
}
```

C. Program Sensor Ultrasonik

```
int trigPin = 12;  
int echoPin = 14;  
int durasi, jarak;  
void setup() {  
    Serial.begin(115200);  
    pinMode(trigPin, OUTPUT);  
    pinMode(echoPin, INPUT);  
}
```

```
void loop() {
    digitalWrite(trigPin, LOW);
    delayMicroseconds(8);
    digitalWrite(trigPin, HIGH);
    delayMicroseconds(8);
    digitalWrite(trigPin, LOW);
    delayMicroseconds(8);
    durasi = pulseIn(echoPin, HIGH);
    jarak = durasi * 0.034 / 2 ;
    Serial.println(jarak);
    delay(500);
}
```

D. Program Pakan Ikan

```
#include <ESP8266WiFi.h>
#include <FirebaseArduino.h>
#define FIREBASE_HOST "coba-default-
rtbd.firebaseio.com"
#define FIREBASE_AUTH
"XFD2vh29PFnggoxJA08k1KGL6dWROgHMe2N1Oh"
#define WIFI_SSID "Samsung A22"
#define WIFI_PASSWORD "qwer1234"
#include "RTClib.h"
RTC_DS3231 rtc;
int jam, menit, detik, jam1, jam2, menit1, menit2;
#include<Servo.h>
Servo motorServo;
void setup() {
    Serial.begin(115200);
    motorServo.attach(16);
#ifndef ESP8266
    while (!Serial);
#endif
    if (! rtc.begin()) {
        Serial.println("RTC Tidak Ditemukan");
```

```

    Serial.flush();
    abort();
}
//rtc.adjust(DateTime(F(__DATE__), F(__TIME__)));
// rtc.adjust(DateTime(2022, 5, 26, 23, 26, 0));
WiFi.begin(WIFI_SSID, WIFI_PASSWORD);
Serial.print("connecting");
while (WiFi.status() != WL_CONNECTED) {
    Serial.print(".");
    delay(500);
}
Serial.println();
Serial.print("connected: ");
Serial.println(WiFi.localIP());

Firebase.begin(FIREBASE_HOST, FIREBASE_AUTH);
}

void loop() {
    DateTime now = rtc.now();
    jam   = now.hour(), DEC;
    menit = now.minute(), DEC;
    detik = now.second(), DEC;
    Serial.println(String() + jam + ":" + menit + ":" + detik);
    Serial.println();
    String j1, j2, m1, m2;
    j1 = Firebase.getString("absd/jam1");
    m1 = Firebase.getString("absd/menit1");
    j2 = Firebase.getString("absd/jam2");
    m2 = Firebase.getString("absd/menit2");
    jam1 = j1.toInt ();
    menit1 = m1.toInt();
    jam2 = j2.toInt ();
    menit2 = m2.toInt();
}

```

```
if(jam == jam1 & menit == menit1 & detik <= 30 || jam ==  
jam2 & menit == menit2 & detik<=30){  
    motorServo.write(180);  
    delay(500);  
    motorServo.write(0);  
    delay(500);  
}  
}  
}
```

E. **Program Penggantian Air**

```
int relay1 = 2;  
int relay2 = 13;  
void setup() {  
    Serial.begin(115200);  
    pinMode(relay1, OUTPUT);  
    pinMode(relay2, OUTPUT);  
}  
void loop() {  
    if (kekeruhan>=10){      // kondisi keruh  
        if(jarak>=7 && jarak<=20){  
            digitalWrite(relay1,HIGH);  
            digitalWrite(relay2,LOW);  
            delay(500);  
        }  
        else if(jarak>=23 ){      // jarak setengah  
            digitalWrite(relay1,LOW);  
            delay(500);  
        }  
        else if(jarak>=10 ){      // isi  
            digitalWrite(relay2,HIGH);  
            delay(500);  
        }  
        else if(jarak<=10 && a==1){      // jarak penuh  
            digitalWrite(relay2,LOW);  
            delay(500);  
    }
```

```
    }
}
else if(kekeruhan <=10){
    digitalWrite(relay1,LOW);
    if (jarak>=10){
        digitalWrite(relay2,HIGH);
        delay(500);
    }

    else if(jarak<=10){
        digitalWrite(relay2,LOW);
        delay(500);
    }
}
```

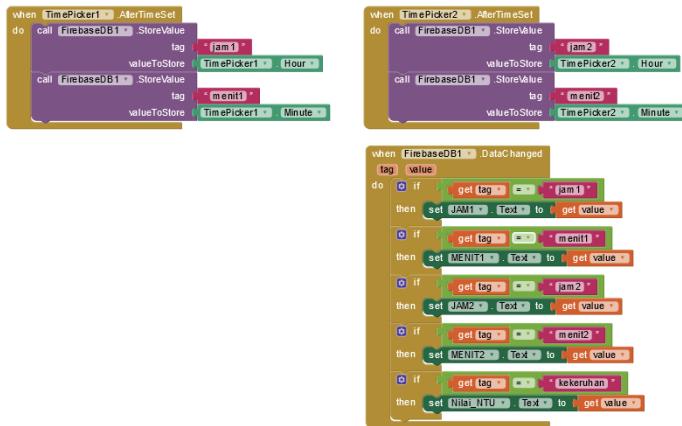
LAMPIRAN B

Tampilan Aplikasi Android



LAMPIRAN C

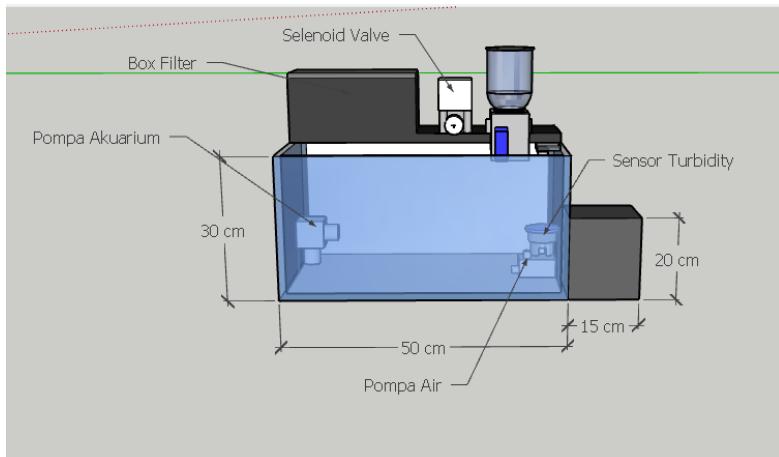
Blok Program Aplikasi Android



LAMPIRAN D

Desain Mekanik Alat

1. Tampak Depan



2. Tampak Samping

